

# Structural Equation Models: The General Case<sup>1</sup>

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# Features of Structural Equation Models

- Multiple equations.
- All the variables are random.
- An explanatory variable in one equation can be the response variable in another equation.
- Models are represented by path diagrams.
- Identifiability is always an issue.
- The statistical models are models of influence. They are often called *causal models*.

## Correlation versus Causation

- The path diagrams deliberately imply influence. If  $A \rightarrow B$ , we are saying  $A$  *contributes* to  $B$ , or partly *causes* it.
- Data are usually observational. The correlation-causation issue does not go away.
- You may be able to argue on theoretical grounds that  $A \rightarrow B$  is more believable than  $B \rightarrow A$ .
- If you have a causal model, you may be able to test whether it's compatible with the data.

## Modest changes in notation

$$Y_{i,1} = \alpha_1 + \gamma_1 X_{i,1} + \gamma_2 X_{i,2} + \epsilon_{i,1}$$

$$Y_{i,2} = \alpha_2 + \beta Y_{i,1} + \epsilon_{i,2}$$

- Regression coefficients (links between exogenous variables and endogenous variables) are now called gamma instead of beta.
- Betas are used for links between endogenous variables.
- Intercepts are alphas but they will soon disappear.

## Losing the intercepts and expected values

- Mostly the intercepts and expected values are not identifiable anyway, as in multiple regression with measurement error.
- We have a chance to identify a *function* of the parameter vector – the parameters that appear in the covariance matrix  $\Sigma$  of an observable data vector.  $\Sigma = cov(\mathbf{D}_i)$ .
- Denote the vector of parameters that appear in  $\Sigma$  by  $\theta$ .
- Re-parameterize. The new parameter vector is  $(\theta, \mu)$ , where  $\mu = E(\mathbf{D}_i)$ .
- Estimate  $\mu$  with  $\bar{\mathbf{D}}$ , forget it, and concentrate on  $\theta$ .
- To make calculation of the covariance matrix easier, write the model equations in centered form. The little letters  $c$  over the variables are invisible.
- From this point on the models *seemingly* have zero means and no intercepts.

# A General Two-Stage Model

Stage 1 is the latent variable model and Stage 2 is the measurement model.

$$\mathbf{Y}_i = \beta \mathbf{Y}_i + \Gamma \mathbf{X}_i + \epsilon_i$$

$$\mathbf{F}_i = \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix}$$

$$\mathbf{D}_i = \Lambda \mathbf{F}_i + \mathbf{e}_i$$

- $\mathbf{D}_i$  (the data) are observable. All other variables are latent.
- $\mathbf{Y}_i = \beta \mathbf{Y}_i + \Gamma \mathbf{X}_i + \epsilon_i$  is called the *Latent Variable Model*.
- The latent vectors  $\mathbf{X}_i$  and  $\mathbf{Y}_i$  are collected into a *factor*  $\mathbf{F}_i$ . This is *not* a categorical explanatory variable, the usual meaning of “factor” in experimental design.
- $\mathbf{D}_i = \Lambda \mathbf{F}_i + \mathbf{e}_i$  is called the *Measurement Model*.

$$\mathbf{Y}_i = \boldsymbol{\beta}\mathbf{Y}_i + \boldsymbol{\Gamma}\mathbf{X}_i + \boldsymbol{\epsilon}_i \quad \mathbf{F}_i = \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix} \quad \mathbf{D}_i = \boldsymbol{\Lambda}\mathbf{F}_i + \mathbf{e}_i$$

- $\mathbf{Y}_i$  is a  $q \times 1$  random vector.
- $\boldsymbol{\beta}$  is a  $q \times q$  matrix of constants with zeros on the main diagonal.
- $\mathbf{X}_i$  is a  $p \times 1$  random vector.
- $\boldsymbol{\Gamma}$  is a  $q \times p$  matrix of constants.
- $\boldsymbol{\epsilon}_i$  is a  $q \times 1$  random vector.
- $\mathbf{F}_i$  ( $F$  for Factor) is just  $\mathbf{X}_i$  stacked on top of  $\mathbf{Y}_i$ . It is a  $(p + q) \times 1$  random vector.
- $\mathbf{D}_i$  is a  $k \times 1$  random vector. Sometimes,  $\mathbf{D}_i = \begin{pmatrix} \mathbf{W}_i \\ \mathbf{V}_i \end{pmatrix}$ .
- $\boldsymbol{\Lambda}$  is a  $k \times (p + q)$  matrix of constants: “factor loadings.”
- $\mathbf{e}_i$  is a  $k \times 1$  random vector.
- $\mathbf{X}_i$ ,  $\boldsymbol{\epsilon}_i$  and  $\mathbf{e}_i$  are independent.

# Covariance matrices

## More notation

$$\mathbf{Y}_i = \beta \mathbf{Y}_i + \mathbf{\Gamma} \mathbf{X}_i + \boldsymbol{\epsilon}_i$$

$$\mathbf{F}_i = \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix}$$

$$\mathbf{D}_i = \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i$$

$$\text{cov}(\mathbf{X}_i) = \mathbf{\Phi}_x$$

$$\text{cov}(\boldsymbol{\epsilon}_i) = \mathbf{\Psi}$$

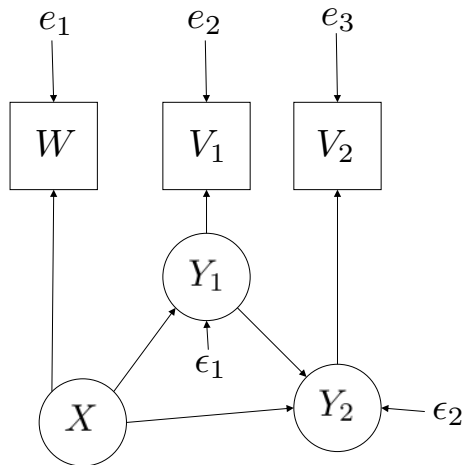
$$\text{cov}(\mathbf{F}_i) = \mathbf{\Phi} = \begin{pmatrix} \text{cov}(\mathbf{X}_i) & \text{cov}(\mathbf{X}_i, \mathbf{Y}_i) \\ \text{cov}(\mathbf{Y}_i, \mathbf{X}_i) & \text{cov}(\mathbf{Y}_i) \end{pmatrix} = \begin{pmatrix} \mathbf{\Phi}_{11} & \mathbf{\Phi}_{12} \\ \mathbf{\Phi}_{12}^\top & \mathbf{\Phi}_{22} \end{pmatrix}$$

$$\text{cov}(\mathbf{e}_i) = \mathbf{\Omega}$$

$$\text{cov}(\mathbf{D}_i) = \mathbf{\Sigma}$$



## Example: A Path Model with Measurement Error



$$Y_{i,1} = \gamma_1 X_i + \epsilon_{i,1}$$

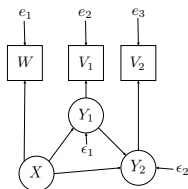
$$Y_{i,2} = \beta Y_{i,1} + \gamma_2 X_i + \epsilon_{i,2}$$

$$W_i = X_i + e_{i,1}$$

$$V_{i,1} = Y_{i,1} + e_{i,2}$$

$$V_{i,2} = Y_{i,2} + e_{i,3}$$

# Matrix Form



$$Y_{i,1} = \gamma_1 X_i + \epsilon_{i,1}$$

$$Y_{i,2} = \beta Y_{i,1} + \gamma_2 X_i + \epsilon_{i,2}$$

$$W_i = X_i + e_{i,1}$$

$$V_{i,1} = Y_{i,1} + e_{i,2}$$

$$V_{i,2} = Y_{i,2} + e_{i,3}$$

$$\mathbf{Y}_i = \boldsymbol{\beta} \mathbf{Y}_i + \boldsymbol{\Gamma} \mathbf{X}_i + \boldsymbol{\epsilon}_i$$

$$\mathbf{F}_i = \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix}$$

$$\mathbf{D}_i = \boldsymbol{\Lambda} \mathbf{F}_i + \mathbf{e}_i$$

$$\begin{pmatrix} \mathbf{Y}_i \\ Y_{i,1} \\ Y_{i,2} \end{pmatrix} = \begin{pmatrix} \boldsymbol{\beta} \\ 0 & 0 \\ \beta & 0 \end{pmatrix} \begin{pmatrix} \mathbf{Y}_i \\ Y_{i,1} \\ Y_{i,2} \end{pmatrix} + \begin{pmatrix} \boldsymbol{\Gamma} \\ \gamma_1 \\ \gamma_2 \end{pmatrix} \mathbf{X}_i + \begin{pmatrix} \boldsymbol{\epsilon}_i \\ \epsilon_{i,1} \\ \epsilon_{i,2} \end{pmatrix}$$

$$\begin{pmatrix} \mathbf{D}_i \\ W_i \\ V_{i,1} \\ V_{i,2} \end{pmatrix} = \begin{pmatrix} \boldsymbol{\Lambda} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \mathbf{F}_i \\ X_i \\ Y_{i,1} \\ Y_{i,2} \end{pmatrix} + \begin{pmatrix} \mathbf{e}_i \\ e_{i,1} \\ e_{i,2} \\ e_{i,3} \end{pmatrix}$$

## Observable variables in the “latent” variable model

$$\mathbf{Y}_i = \beta \mathbf{Y}_i + \Gamma \mathbf{X}_i + \epsilon_i$$

Fairly common

- These present no problem.
- Let  $P(e_j = 0) = 1$ , so  $Var(e_j) = 0$ .
- And  $Cov(e_i, e_j) = 0$
- Because if  $P(e_j = 0) = 1$ ,

$$\begin{aligned}Cov(e_i, e_j) &= E(e_i e_j) - E(e_i)E(e_j) \\ &= E(e_i \cdot 0) - E(e_i) \cdot 0 \\ &= 0 - 0 = 0\end{aligned}$$

- In  $\Omega = cov(\mathbf{e}_i)$ , column  $j$  (and row  $j$ ) are all zeros.
- $\Omega$  singular, no problem.

## What should you be able to do?

- Given a path diagram, write the model equations and say which exogenous variables are correlated with each other.
- Given the model equations and information about which exogenous variables are correlated with each other, draw the path diagram.
- Given either piece of information, write the model in matrix form and say what all the matrices are.
- Calculate model covariance matrices.
- Check identifiability.

## Recall the notation

$$\mathbf{Y}_i = \beta \mathbf{Y}_i + \Gamma \mathbf{X}_i + \epsilon_i$$

$$\mathbf{F}_i = \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix}$$

$$\mathbf{D}_i = \Lambda \mathbf{F}_i + \mathbf{e}_i$$

$$\text{cov}(\mathbf{X}_i) = \Phi_x$$

$$\text{cov}(\epsilon_i) = \Psi$$

$$\text{cov}(\mathbf{F}_i) = \Phi = \begin{pmatrix} \text{cov}(\mathbf{X}_i) & \text{cov}(\mathbf{X}_i, \mathbf{Y}_i) \\ \text{cov}(\mathbf{Y}_i, \mathbf{X}_i) & \text{cov}(\mathbf{Y}_i) \end{pmatrix} = \begin{pmatrix} \Phi_{11} & \Phi_{12} \\ \Phi_{12}^\top & \Phi_{22} \end{pmatrix}$$

$$\text{cov}(\mathbf{e}_i) = \Omega$$

$$\text{cov}(\mathbf{D}_i) = \Sigma$$

Calculate a general expression for  $\Sigma(\theta)$ .

For the latent variable model, calculate  $\Phi = cov(\mathbf{F}_i)$

Have  $cov(\mathbf{X}_i) = \Phi_x$ , need  $cov(\mathbf{Y}_i)$  and  $cov(\mathbf{X}_i, \mathbf{Y}_i)$

$$\mathbf{Y}_i = \beta \mathbf{Y}_i + \Gamma \mathbf{X}_i + \epsilon_i$$

$$\Rightarrow \mathbf{Y}_i - \beta \mathbf{Y}_i = \Gamma \mathbf{X}_i + \epsilon_i$$

$$\Rightarrow \mathbf{I} \mathbf{Y}_i - \beta \mathbf{Y}_i = \Gamma \mathbf{X}_i + \epsilon_i$$

$$\Rightarrow (\mathbf{I} - \beta) \mathbf{Y}_i = \Gamma \mathbf{X}_i + \epsilon_i$$

$$\Rightarrow (\mathbf{I} - \beta)^{-1} (\mathbf{I} - \beta) \mathbf{Y}_i = (\mathbf{I} - \beta)^{-1} (\Gamma \mathbf{X}_i + \epsilon_i)$$

$$\Rightarrow \mathbf{Y}_i = (\mathbf{I} - \beta)^{-1} (\Gamma \mathbf{X}_i + \epsilon_i)$$

So,

$$\begin{aligned} cov(\mathbf{Y}_i) &= (\mathbf{I} - \beta)^{-1} cov(\Gamma \mathbf{X}_i + \epsilon_i) (\mathbf{I} - \beta)^{-1 \top} \\ &= (\mathbf{I} - \beta)^{-1} (cov(\Gamma \mathbf{X}_i) + cov(\epsilon_i)) (\mathbf{I} - \beta^{\top})^{-1} \\ &= (\mathbf{I} - \beta)^{-1} (\Gamma \Phi_{11} \Gamma^{\top} + \Psi) (\mathbf{I} - \beta^{\top})^{-1} \end{aligned}$$

For the measurement model, calculate  $\Sigma = cov(\mathbf{D}_i)$

$$\begin{aligned}\mathbf{D}_i &= \mathbf{\Lambda}\mathbf{F}_i + \mathbf{e}_i \\ \Rightarrow cov(\mathbf{D}_i) &= cov(\mathbf{\Lambda}\mathbf{F}_i + \mathbf{e}_i) \\ &= cov(\mathbf{\Lambda}\mathbf{F}_i) + cov(\mathbf{e}_i) \\ &= \mathbf{\Lambda}cov(\mathbf{F}_i)\mathbf{\Lambda}^\top + cov(\mathbf{e}_i) \\ &= \mathbf{\Lambda}\mathbf{\Phi}\mathbf{\Lambda}^\top + \mathbf{\Omega} \\ &= \mathbf{\Sigma}\end{aligned}$$

# Two-stage Proofs of Identifiability

Stage 1 is the latent variable model and Stage 2 is the measurement model.

- Show the parameters of the latent variable model  $(\beta, \Gamma, \Phi_{11}, \Psi)$  can be recovered from  $\Phi = cov(\mathbf{F}_i)$ .
- Show the parameters of the measurement model  $(\Lambda, \Phi, \Omega)$  can be recovered from  $\Sigma = cov(\mathbf{D}_i)$ .
- This means all the parameters can be recovered from  $\Sigma$ .
- Break a big problem into two smaller ones.
- Develop *rules* for checking identifiability at each stage.
- Just look at the path diagram.



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<http://www.utstat.toronto.edu/~brunner/oldclass/431s17>