Double Measurement Regression[1]

STA431 Winter/Spring 2015

[1] See last slide for copyright information.

Overview

Seeking identifiability

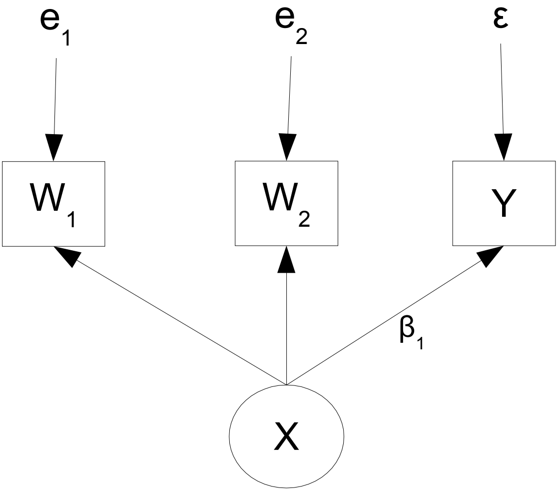
We have seen that in simple regression, parameters of a model with measurement error are not identifiable.

$$\begin{aligned} Y_i &= \alpha_1 + \beta_1 X_i + \epsilon_i \\ W_i &= \nu + X_i + e_i, \end{aligned}$$

- For example, X might be number of acres planted and Y might be crop yield.
- Plan the statistical analysis in advance.
- Take 2 independent measurements of the explanatory variable.
- Say, farmer's report and aerial photograph.

Double measurement

Of the explanatory variable



Model

Independently for $i = 1, \ldots, n$, let

$$
\begin{aligned}
W_{i,1} &= \nu_1 + X_i + e_{i,1} \\
W_{i,2} &= \nu_2 + X_i + e_{i,2} \\
Y_i &= \beta_0 + \beta_1 X_i + \epsilon_i,
\end{aligned}
$$

where

- X_i is normally distributed with mean μ_x and variance $\phi > 0$
- ϵ_i is normally distributed with mean zero and variance $\psi > 0$
- $e_{i,1}$ is normally distributed with mean zero and variance $\omega_1 > 0$
- $e_{i,2}$ is normally distributed with mean zero and variance $\omega_2 > 0$
- $X_i, e_{i,1}, e_{i,2}$ and ϵ_i are all independent.

Does this model pass the test of the Parameter Count Rule?

$$
\begin{aligned}
W_{i,1} &= \nu_1 + X_i + e_{i,1} \\
W_{i,2} &= \nu_2 + X_i + e_{i,2} \\
Y_i &= \beta_0 + \beta_1 X_i + \epsilon_i,
\end{aligned}
$$

$\boldsymbol{\theta} = (\nu_1, \nu_2, \beta_0, \mu_x, \beta_1, \phi, \psi, \omega_1, \omega_2)$: 9 parameters.

- Three expected values, three variances and three covariances: 9 moments.
- Yes. There are nine moment structure equations in nine unknown parameters. Identifiability is possible, but not guaranteed.

What is the distribution of the sample data?

Calculate the moments as a function of the model parameters

The model implies that the triples $\mathbf{D}_i = (W_{i,1}, W_{i,2}, Y_i)^\top$ are independent multivarate normal with

$$E(\mathbf{D}_i) = E\left(\begin{array}{c} W_{i,1} \\ W_{i,1} \\ Y_i \end{array}\right) = \left(\begin{array}{c} \mu_1 \\ \mu_2 \\ \mu_3 \end{array}\right) = \left(\begin{array}{c} \mu_x + \nu_1 \\ \mu_x + \nu_2 \\ \beta_0 + \beta_1 \mu_x \end{array}\right),$$

and variance covariance matrix $V(\mathbf{D}_i) = \mathbf{\Sigma} =$

$$\left(\begin{array}{ccc} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33} \end{array}\right) = \left(\begin{array}{ccc} \phi + \omega_1 & \phi & \beta_1 \phi \\ & \phi + \omega_2 & \beta_1 \phi \\ & & \beta_1^2 \phi + \psi \end{array}\right).$$

Are the parameters in the covariance matrix identifiable?

Six equations in five unknowns

$$\left(\begin{array}{ccc} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33} \end{array} \right) = \left(\begin{array}{ccc} \phi+\omega_1 & \phi & \beta_1\phi \\ & \phi+\omega_2 & \beta_1\phi \\ & & \beta_1^2\phi+\psi \end{array} \right).$$

$$\begin{aligned} \phi &= \sigma_{12} \\ \omega_1 &= \sigma_{11}-\sigma_{12} \\ \omega_2 &= \sigma_{22}-\sigma_{12} \\ \beta_1 &= \frac{\sigma_{13}}{\sigma_{12}} \\ \psi &= \sigma_{33}-\beta_1^2\phi = \sigma_{33}-\frac{\sigma_{13}^2}{\sigma_{12}} \end{aligned}$$

Yes.

What about the expected values?

Model equations again:

$$
\begin{array}{rcl}
W_{i,1} & = & \nu_1 + X_i + e_{i,1} \\
W_{i,2} & = & \nu_2 + X_i + e_{i,2} \\
Y_i & = & \beta_0 + \beta_1 X_i + \epsilon_i,
\end{array}
$$

Expected values:

$$
\begin{array}{rcl}
\mu_1 & = & \nu_1 + \mu_x \\
\mu_2 & = & \nu_2 + \mu_x \\
\mu_3 & = & \beta_0 + \beta_1 \mu_x
\end{array}
$$

Four parameters appear only in the expected values: $\nu_1, \nu_2, \mu_x, \beta_0$.

- Three equations in four unknowns, even assuming β_1 known.
- Parameter count rule applies.
- But we don't need it because these are linear equations.
- Re-parameterize.

Re-parameterize

$\mu_1 = \nu_1 + \mu_x \qquad \mu_2 = \nu_2 + \mu_x \qquad \mu_3 = \beta_0 + \beta_1\mu_x$

- Absorb $\nu_1, \nu_2, \mu_x, \beta_0$ into $\boldsymbol{\mu}$.
- Parameter was $\boldsymbol{\theta} = (\nu_1, \nu_2, \beta_0, \mu_x, \ \beta_1, \phi, \psi, \omega_1, \omega_2)$
- Now it's $\boldsymbol{\theta} = (\mu_1, \mu_2, \mu_3, \ \beta_1, \phi, \psi, \omega_1, \omega_2)$.
- Dimension of the parameter space is now one less.
- We haven't lost much.
- Especially because the model was already re-parameterized.
- Of course there is measurement error in Y. Recall

$$\begin{aligned} Y &= \alpha + \beta X + \epsilon \\ V &= \nu_0 + Y + e \\ &= \nu_0 + (\alpha + \beta X + \epsilon) + e \\ &= (\nu_0 + \alpha) + \beta X + (\epsilon + e) \\ &= \beta_0 + \beta X + \epsilon' \end{aligned}$$

Re-parameterization

- Re-parameterization makes maximum likelihood possible.
- Otherwise the maximum is not unique and it's a mess.
- Estimate $\boldsymbol{\mu}$ with $\overline{\mathbf{D}}$ and it simply disappears from

$$L(\boldsymbol{\mu}, \boldsymbol{\Sigma}) = |\boldsymbol{\Sigma}|^{-n/2}(2\pi)^{-np/2} \exp -\frac{n}{2}\left\{tr(\widehat{\boldsymbol{\Sigma}}\boldsymbol{\Sigma}^{-1}) + (\overline{\mathbf{D}} - \boldsymbol{\mu})^\top \boldsymbol{\Sigma}^{-1}(\overline{\mathbf{D}} - \boldsymbol{\mu})\right\}$$

- This step is so common it becomes silent.
- Model equations are often written in centered form.
- It's more compact, and calculation of the covariance matrix is easier.

Back to the covariance structure equations

$$\begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33} \end{pmatrix} = \begin{pmatrix} \phi+\omega_1 & \phi & \beta_1\phi \\ & \phi+\omega_2 & \beta_1\phi \\ & & \beta_1^2\phi+\psi \end{pmatrix}.$$

- Notice that the model dictates $\sigma_{1,3} = \sigma_{2,3}$.
- There are two ways to solve for β_1:
  $\beta_1 = \frac{\sigma_{13}}{\sigma_{12}}$ and $\beta_1 = \frac{\sigma_{23}}{\sigma_{12}}$.
- Does this mean the solution for β_1 is not "unique?"
- No; everything is okay. Because $\sigma_{1,3} = \sigma_{2,3}$, the two solutions are actually the same.
- If a parameter can be recovered from the moments in any way at all, it is identifiable.

Testing goodness of fit.

$$\left(\begin{array}{ccc}\sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33}\end{array}\right) = \left(\begin{array}{ccc}\phi+\omega_1 & \phi & \beta_1\phi \\ & \phi+\omega_2 & \beta_1\phi \\ & & \beta_1^2\phi+\psi\end{array}\right).$$

- $\sigma_{1,3} = \sigma_{2,3}$ is a *model-induced constraint* upon $\boldsymbol{\Sigma}$.
- It's a testable null hypothesis.
- If rejected, the model is called into question.
- Likelihood ratio test comparing this model to a completely unrestricted multivariate normal model:

$$G^2 = -2\ln\frac{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)}{L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}})}$$

- It's n times the SAS "objective function" at the MLE.
- A likelihood ratio test for goodness of fit.
- Valuable even if the data are not normal.

The Reproduced Covariance Matrix

- $\boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})$ is called the *reproduced covariance matrix.*
- It is the covariance matrix of the observable data, written as a function of the model parameters and evaluated at the MLE.

$$\boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}}) = \left(\begin{array}{ccc} \widehat{\phi}+\widehat{\omega}_1 & \widehat{\phi} & \widehat{\beta}_1\widehat{\phi} \\ & \widehat{\phi}+\widehat{\omega}_2 & \widehat{\beta}_1\widehat{\phi} \\ & & \widehat{\beta}_1^2\widehat{\phi}+\widehat{\psi} \end{array} \right)$$

- The reproduced covariance matrix obeys all model-induced constraints, while $\widehat{\boldsymbol{\Sigma}}$ does not.
- But if the model is right they should be close.
- This is a way to think about the likelihood ratio test for goodness of fit.

General pattern for testing goodness of fit

Usually works

- Suppose there are k moment structure equations in p parameters, and all the parameters are identifiable.
- If $p < k$, call the parameter vector *over-identifiable.*
- Only needed p equations to solve for $\boldsymbol{\theta}$.
- Substituting the solutions (in terms of σ_{ij}) back into the unused equations would yield $k-p$ equality constraints on $\boldsymbol{\Sigma}$.
- Test those constraints with $G^2 = -2 \ln \frac{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)}{L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}})}$.
- $df = k-p$
- Don't need to actually derive the constraints – just count them.

With the same number of equations and parameters

- If the parameter is identifiable, call it *just identifiable*.
- Parameters are 1-1 with those of an unrestricted multivariate normal.
- Call the model "saturated."
- There are no equality constraints on $\boldsymbol{\Sigma}$.
- No likelihood ratio test ($G^2 = -2\ln\frac{L\left(\overline{\mathbf{D}},\boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)}{L(\overline{\mathbf{D}},\widehat{\boldsymbol{\Sigma}})} = 0$).
- This is what happens in regression with all observed variables.

How to proceed

- Verify identifiability.
- If the model is over-identified, test goodness of fit.
- If it passes (non-significant), proceed.
- Now think of your model as a “full,” or unrestricted model.
- Compared to some (even more) reduced model that is restricted by a null hypothesis like $\beta_1 = 0$.
- Fit the reduced model.
- Subtract goodness of fit (G^2 or “chi-square”) statistics to test H_0.

Subtract goodness of fit statistics

G^2 tests the full model against the saturated model, and G_0^2 tests the reduced model against the saturated model.

$$
\begin{aligned}
G_0^2 - G^2 &= -2\ln \frac{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}}_0)\right)}{L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}})} - -2\ln \frac{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)}{L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}})} \\
&= -2\left(\ln L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}}_0)\right) - \ln L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}}) - \ln L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)\right. \\
&\qquad \left. + \ln L(\overline{\mathbf{D}}, \widehat{\boldsymbol{\Sigma}})\right) \\
&= -2\ln \frac{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}}_0)\right)}{L\left(\overline{\mathbf{D}}, \boldsymbol{\Sigma}(\widehat{\boldsymbol{\theta}})\right)}
\end{aligned}
$$

If the software gives you $\frac{n-1}{n}G^2$, use that.

Further comments

- Models with non-identifiable parameters can imply testable equality constraints, but testing them is not automatic.
- Models can imply *inequality* constraints on $\boldsymbol{\Sigma}$, too.
- Recall the solutions

$$
\begin{aligned}
\phi &= \sigma_{12} \\
\omega_1 &= \sigma_{11} - \sigma_{12} \\
\omega_2 &= \sigma_{22} - \sigma_{12} \\
\beta_1 &= \frac{\sigma_{13}}{\sigma_{12}} \\
\psi &= \sigma_{33} - \beta_1^2\phi = \sigma_{33} - \frac{\sigma_{13}^2}{\sigma_{12}}
\end{aligned}
$$

We get four inequality constraints.

Four inequality constraints on $\boldsymbol{\Sigma}$

$$\left(\begin{array}{ccc} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ & \sigma_{22} & \sigma_{23} \\ & & \sigma_{33} \end{array}\right) = \left(\begin{array}{ccc} \phi+\omega_1 & \phi & \beta_1\phi \\ & \phi+\omega_2 & \beta_1\phi \\ & & \beta_1^2\phi+\psi \end{array}\right).$$

$$\begin{array}{rcl} \phi & = & \sigma_{12} > 0 \\ \omega_1 & = & \sigma_{11} - \sigma_{12} > 0 \\ \omega_2 & = & \sigma_{22} - \sigma_{12} > 0 \\ \psi & = & \sigma_{33} - \frac{\sigma_{13}^2}{\sigma_{12}} > 0 \end{array}$$

Inequality constraints

- Inequality constraints arise because variances are positive.
- Or more generally, covariance matrices are positive definite.
- Could inequality constraints be violated in numerical maximum likelihood?
- Definitely.
- But only a little by sampling error if the model is correct.
- So maybe it's not so dumb to test hypotheses like $H_0 : \omega_1 = 0$.
- Since the model says $\omega_1 = \sigma_{11} - \sigma_{12}$.

Little SAS Example

```
/**************************** Babydouble.sas ****************************/
title 'Simple double measurement with proc calis';
title2 'Jerry Brunner:  Student Number 999999999';

data baby;
     infile '/folders/myfolders/431s15/Babydouble.data.txt'
             firstobs=2;
     input id W1 W2 Y;

proc calis pcorr vardef=n;
     /* See reproduced covariance matrix,
        Use true MLE and get exact G^2 */
 title3 'Fit the centered model';
     var W1 W2 Y;  /* Declare observed variables */
     lineqs        /* Model equations, separated by commas. */
        Y  = beta1*F + epsilon, /* Latent variables begin with the letter F */
        W1 = F + e1,
        W2 = F + e2;
     variance      /* Declare variance parameters. */
        F = phi, epsilon = psi, e1=omega1, e2=omega2;
```

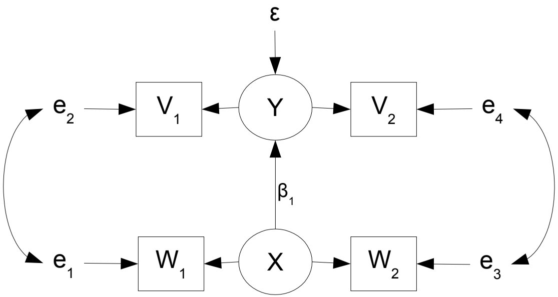
Results

Click **Here** for the output. This link will probably be broken once the term is over. See the course website for another route to the output file:

`http://www.utstat.toronto.edu/~brunner/oldclass/431s15`

An extension of the double measurement design

Double measurement can help solve a big problem: Correlated measurement error.



- The main idea is that **X** and **Y** are each measured twice, perhaps at different times using different methods.
- Measurement errors may be correlated within sets but not between sets.

Double Measurement Regression: A Two-Stage Model

$$
\begin{aligned}
\mathbf{Y}_i &= \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \mathbf{X}_i + \boldsymbol{\epsilon}_i \\
\mathbf{F}_i &= \left(\begin{array}{c} \mathbf{X}_i \\ \mathbf{Y}_i \end{array} \right) \\
\mathbf{D}_{i,1} &= \boldsymbol{\nu}_1 + \mathbf{F}_i + \mathbf{e}_{i,1} \\
\mathbf{D}_{i,2} &= \boldsymbol{\nu}_2 + \mathbf{F}_i + \mathbf{e}_{i,2}
\end{aligned}
$$

Observable variables are $\mathbf{D}_{i,1}$ and $\mathbf{D}_{i,2}$: both are $(p+q) \times 1$.

$E(\mathbf{X}_i) = \boldsymbol{\mu}_x$, $V(\mathbf{X}_i) = \boldsymbol{\Phi}_x$, $V(\boldsymbol{\epsilon}_i) = \boldsymbol{\Psi}$, $V(\mathbf{e}_{i,1}) = \boldsymbol{\Omega}_1$, $V(\mathbf{e}_{i,2}) = \boldsymbol{\Omega}_2$. Also, $\mathbf{X}_i$, $\boldsymbol{\epsilon}_i$, $\mathbf{e}_{i,1}$ and $\mathbf{e}_{i,2}$ are independent.

Measurement errors may be correlated

Look at the measurement model

$$
\begin{aligned}
\mathbf{F}_i &= \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix} \\
\mathbf{D}_{i,1} &= \boldsymbol{\nu}_1 + \mathbf{F}_i + \mathbf{e}_{i,1} \\
\mathbf{D}_{i,2} &= \boldsymbol{\nu}_2 + \mathbf{F}_i + \mathbf{e}_{i,2}
\end{aligned}
$$

$$
\begin{aligned}
V(\mathbf{e}_{i,1}) &= \boldsymbol{\Omega}_1 = \left(\begin{array}{c|c} \boldsymbol{\Omega}_{11} & \boldsymbol{\Omega}_{12} \\ \hline \boldsymbol{\Omega}_{12}^\top & \boldsymbol{\Omega}_{22} \end{array}\right) \\
V(\mathbf{e}_{i,2}) &= \boldsymbol{\Omega}_2 = \left(\begin{array}{c|c} \boldsymbol{\Omega}_{33} & \boldsymbol{\Omega}_{34} \\ \hline \boldsymbol{\Omega}_{34}^\top & \boldsymbol{\Omega}_{44} \end{array}\right)
\end{aligned}
$$

Expected values of the observable variables

$\mathbf{D}_{i,1} = \boldsymbol{\nu}_1 + \mathbf{F}_i + \mathbf{e}_{i,1}$ and $\mathbf{D}_{i,2} = \boldsymbol{\nu}_2 + \mathbf{F}_i + \mathbf{e}_{i,2}$

$$E(\mathbf{D}_{i,1}) = \left(\begin{array}{c} \boldsymbol{\mu}_{1,1} \\ \boldsymbol{\mu}_{1,2} \end{array} \right) = \left(\begin{array}{c} \boldsymbol{\nu}_{1,1} + E(\mathbf{X}_i) \\ \boldsymbol{\nu}_{1,2} + E(\mathbf{Y}_i) \end{array} \right) = \left(\begin{array}{c} \boldsymbol{\nu}_{1,1} + \boldsymbol{\mu}_x \\ \boldsymbol{\nu}_{1,2} + \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \boldsymbol{\mu}_x \end{array} \right)$$

$$E(\mathbf{D}_{i,2}) = \left(\begin{array}{c} \boldsymbol{\mu}_{2,1} \\ \boldsymbol{\mu}_{2,2} \end{array} \right) = \left(\begin{array}{c} \boldsymbol{\nu}_{2,1} + E(\mathbf{X}_i) \\ \boldsymbol{\nu}_{2,2} + E(\mathbf{Y}_i) \end{array} \right) = \left(\begin{array}{c} \boldsymbol{\nu}_{2,1} + \boldsymbol{\mu}_x \\ \boldsymbol{\nu}_{2,2} + \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \boldsymbol{\mu}_x \end{array} \right)$$

- $\boldsymbol{\nu}_1$, $\boldsymbol{\nu}_2$, $\boldsymbol{\beta}_0$ and $\boldsymbol{\mu}_x$ parameters appear only in expected value, not covariance matrix.
- $\mathbf{X}_i$ is $p \times 1$ and $\mathbf{Y}_i$ is $q \times 1$.
- Even with knowledge of $\boldsymbol{\beta}_0$, $2(p+q)$ equations in $3(p+q)$ unknown parameters.
- Identifying the expected values and intercepts is hopeless.
- Re-parameterize, swallowing them into $\boldsymbol{\mu} = E\left(\begin{array}{c} \mathbf{D}_{i,1} \\ \mathbf{D}_{i,2} \end{array} \right)$.

Stage One: The latent variable model

$$
\begin{aligned}
\mathbf{Y}_i &= \boldsymbol{\beta}_0 + \boldsymbol{\beta}_1 \mathbf{X}_i + \boldsymbol{\epsilon}_i \\
\mathbf{F}_i &= \begin{pmatrix} \mathbf{X}_i \\ \mathbf{Y}_i \end{pmatrix}
\end{aligned}
$$

$V(\mathbf{X}_i) = \boldsymbol{\Phi}_x$, $V(\boldsymbol{\epsilon}_i) = \boldsymbol{\Psi}$, $\mathbf{X}_i$ and $\boldsymbol{\epsilon}_i$ are independent.
Proving identifiability, ...

$$
V(\mathbf{F}_i) = \boldsymbol{\Phi} = \begin{pmatrix} \boldsymbol{\Phi}_{11} & \boldsymbol{\Phi}_{12} \\ \boldsymbol{\Phi}_{12}^\top & \boldsymbol{\Phi}_{22} \end{pmatrix} = \begin{pmatrix} \boldsymbol{\Phi}_x & \boldsymbol{\Phi}_x \boldsymbol{\beta}_1^\top \\ \boldsymbol{\beta}_1 \boldsymbol{\Phi}_x & \boldsymbol{\beta}_1 \boldsymbol{\Phi}_x \boldsymbol{\beta}_1^\top + \boldsymbol{\Psi} \end{pmatrix}
$$

$\boldsymbol{\Phi}_x$, $\boldsymbol{\beta}_1$ and $\boldsymbol{\Psi}$ can be recovered from $\boldsymbol{\Phi}$.

Stage Two: The measurement model

$$\begin{aligned} \mathbf{D}_{i,1} &= \boldsymbol{\nu}_1 + \mathbf{F}_i + \mathbf{e}_{i,1} \\ \mathbf{D}_{i,2} &= \boldsymbol{\nu}_2 + \mathbf{F}_i + \mathbf{e}_{i,2} \end{aligned}$$

$V(\mathbf{e}_{i,1}) = \boldsymbol{\Omega}_1$, $V(\mathbf{e}_{i,2}) = \boldsymbol{\Omega}_2$. Also, $\mathbf{F}_i$, $\mathbf{e}_{i,1}$ and $\mathbf{e}_{i,2}$ are independent.

$$\boldsymbol{\Sigma} = V \left(\begin{array}{c} \mathbf{D}_{i,1} \\ \mathbf{D}_{i,2} \end{array} \right) = \left(\begin{array}{cc} \boldsymbol{\Phi} + \boldsymbol{\Omega}_1 & \boldsymbol{\Phi} \\ \boldsymbol{\Phi} & \boldsymbol{\Phi} + \boldsymbol{\Omega}_2 \end{array} \right)$$

$\boldsymbol{\Phi}$, $\boldsymbol{\Omega}_1$ and $\boldsymbol{\Omega}_2$ can easily be recovered from $\boldsymbol{\Sigma}$.

All the parameters in the covariance matrix are identifiable

- $\boldsymbol{\Phi}_x$, $\boldsymbol{\beta}_1$ and $\boldsymbol{\Psi}$ can be recovered from $\boldsymbol{\Phi} = V(\mathbf{F}_i)$.
- $\boldsymbol{\Phi}$, $\boldsymbol{\Omega}_1$ and $\boldsymbol{\Omega}_2$ can be recovered from $\boldsymbol{\Sigma} = V\left(\begin{array}{c} \mathbf{D}_{i,1} \\ \mathbf{D}_{i,2} \end{array}\right)$.

- Correlated measurement error within sets is allowed.
- This is a big plus, because it's reality.
- Correlated measurement error between sets must be ruled out by careful data collection.
- No need to do the calculations ever again.

The BMI Health Study

- Body Mass Index: Weight in Kilograms divided by Height in Meters Squared.
- Under 18 means underweight, Over 25 means overweight, Over 30 means obese.
- High BMI is associated with poor health, like high blood pressure and high cholesterol.
- People with high BMI tend to be older and fatter.
- *But*, what if you have a high BMI but are in good physical shape (low percent body fat)?

The Question

- If you control for age and percent body fat, is BMI still associated with indicators for poor health?
- But percent body fat (and to a lesser extent, age) are measured with error. Standard ways of controlling for them with ordinary regression are highly suspect.
- Use the double measurement design.

True variables (all latent)

- X_1 = Age
- X_2 = BMI
- X_3 = Percent body fat
- Y_1 = Cholesterol
- Y_2 = Diastolic blood pressure

Measure twice with different personnel at different locations and by different methods

	Measurement Set One	Measurement Set Two
Age	Self report	Passport or birth certificate
BMI	Dr. Office measurements	Lab technician, no shoes, gown
% Body Fat	Tape and calipers, Dr. Office	Submerge in water tank
Cholesterol	Lab 1	Lab 2
Diastolic BP	Blood pressure cuff, Dr. office	Digital readout, mostly automatic

- Set two is of generally higher quality.
- Correlation of measurement errors is unlikely between sets.

Copyright Information