# Exploratory Factor Analysis 

## STA2053: Fall 2022

See last slide for copyright informotion

## Factor Analysis: The Measurement Model

$$
\mathbf{D}_{i}=\mathbf{\Lambda} \mathbf{F}_{i}+\mathbf{e}_{i}
$$



## Example with 2 factors and 8 observed variables

$$
\begin{gathered}
\mathbf{D}_{i}=\mathbf{\Lambda} \mathbf{F}_{i}+\mathbf{e}_{i} \\
\left(\begin{array}{c}
D_{i, 1} \\
D_{i, 2} \\
D_{i, 3} \\
D_{i, 4} \\
D_{i, 5} \\
D_{i, 6} \\
D_{i, 7} \\
D_{i, 8}
\end{array}\right)=\left(\begin{array}{cc}
\lambda_{11} & \lambda_{12} \\
\lambda_{21} & \lambda_{22} \\
\lambda_{31} & \lambda_{32} \\
\lambda_{41} & \lambda_{42} \\
\lambda_{51} & \lambda_{52} \\
\lambda_{61} & \lambda_{62} \\
\lambda_{71} & \lambda_{27} \\
\lambda_{81} & \lambda_{82}
\end{array}\right)\binom{F_{i, 1}}{F_{i, 2}}+\left(\begin{array}{l}
e_{i, 1} \\
e_{i, 2} \\
e_{i, 3} \\
e_{i, 4} \\
e_{i, 5} \\
e_{i, 6} \\
e_{i, 7} \\
e_{i, 8}
\end{array}\right) \\
D_{i, 1}=\lambda_{11} F_{i, 1}+\lambda_{12} F_{i, 2}+e_{i, 1} \\
D_{i, 2}=\lambda_{21} F_{i, 1}+\lambda_{22} F_{i, 2}+e_{i, 2} \text { etc. }
\end{gathered}
$$

The lambda values are called factor loadings.

## Terminology

$$
\begin{aligned}
D_{i, 1} & =\lambda_{11} F_{i, 1}+\lambda_{12} F_{i, 2}+e_{i, 1} \\
D_{i, 2} & =\lambda_{21} F_{i, 1}+\lambda_{22} F_{i, 2}+e_{i, 2} \text { etc. }
\end{aligned}
$$

- The lambda values are called factor loadings.
- $F_{1}$ and $F_{2}$ are sometimes called common factors, because they influence all the observed variables.
- Error terms $\mathrm{e}_{1}, \ldots, \mathrm{e}_{8}$ are sometimes called unique factors, because each one influences only a single observed variable.


## Factor Analysis can be

- Exploratory: The goal is to describe and summarize the data by explaining a large number of observed variables in terms of a smaller number of latent variables (factors). The factors are the reason the observable variables have the correlations they do.
- Confirmatory: Statistical estimation and testing as usual.


## Unconstrained (Exploratory) Factor Analysis



- Arrows from all factors to all observed variables.
- Massively non-identifiable.
- Reasonable, been going on for around 70-100 years, and completely DOOMED TO FAILURE as a method of statistical estimation.


## Calculate the covariance matrix

$$
\begin{aligned}
\mathbf{D}_{i} & =\boldsymbol{\Lambda} \mathbf{F}_{i}+\mathbf{e}_{i} \\
\operatorname{cov}\left(\mathbf{F}_{i}\right) & =\mathbf{\Phi} \\
\operatorname{cov}\left(\mathbf{e}_{i}\right) & =\boldsymbol{\Omega}
\end{aligned}
$$

$\mathbf{F}_{i}$ and $\mathbf{e}_{i}$ independent (multivariate normal)

$$
\operatorname{cov}\left(\mathbf{D}_{i}\right)=\boldsymbol{\Sigma}=\boldsymbol{\Lambda} \boldsymbol{\Phi} \boldsymbol{\Lambda}^{\top}+\boldsymbol{\Omega}
$$

## A Re-parameterization

$$
\boldsymbol{\Sigma}=\boldsymbol{\Lambda} \boldsymbol{\Phi} \boldsymbol{\Lambda}^{\top}+\boldsymbol{\Omega}
$$

Square root matrix: $\boldsymbol{\Phi}=\mathbf{S S}=\mathbf{S S}^{\top}$, so

$$
\begin{aligned}
\boldsymbol{\Lambda} \mathbf{\Phi} \boldsymbol{\Lambda}^{\top} & =\boldsymbol{\Lambda} \mathbf{S S}^{\top} \boldsymbol{\Lambda}^{\top} \\
& =(\boldsymbol{\Lambda} \mathbf{S}) \mathbf{I}\left(\mathbf{S}^{\top} \boldsymbol{\Lambda}^{\top}\right) \\
& =(\boldsymbol{\Lambda} \mathbf{S}) \mathbf{I}(\boldsymbol{\Lambda} \mathbf{S})^{\top} \\
& =\boldsymbol{\Lambda}_{2} \mathbf{I} \boldsymbol{\Lambda}_{2}^{\top}
\end{aligned}
$$

## Parameters are not identifiable

$$
\boldsymbol{\Sigma}=\boldsymbol{\Lambda} \mathbf{\Phi} \boldsymbol{\Lambda}^{\top}+\boldsymbol{\Omega}=\boldsymbol{\Lambda}_{2} \mathbf{I} \mathbf{\Lambda}_{2}^{\top}+\boldsymbol{\Omega}
$$

- Two distinct (Lambda, Phi, Omega) sets give the same Sigma, and hence the same distribution of the data (under normality).
- Actually, there are infinitely many. Let $\mathbf{Q}$ be an arbitrary covariance matrix for $\mathbf{F}$.

$$
\begin{aligned}
\boldsymbol{\Lambda}_{2} \mathbf{I} \mathbf{\Lambda}_{2}^{\top} & =\boldsymbol{\Lambda}_{2} \mathbf{Q}^{-\frac{1}{2}} \mathbf{Q} \mathbf{Q}^{-\frac{1}{2}} \boldsymbol{\Lambda}_{2}^{\top} \\
& =\left(\boldsymbol{\Lambda}_{2} \mathbf{Q}^{-\frac{1}{2}}\right) \mathbf{Q}\left(\mathbf{Q}^{-\frac{1}{2} \top} \boldsymbol{\Lambda}_{2}^{\top}\right) \\
& =\left(\boldsymbol{\Lambda}_{2} \mathbf{Q}^{-\frac{1}{2}}\right) \mathbf{Q}\left(\boldsymbol{\Lambda}_{2} \mathbf{Q}^{-\frac{1}{2}}\right)^{\top} \\
& =\boldsymbol{\Lambda}_{3} \mathbf{Q} \mathbf{\Lambda}_{3}^{\top}
\end{aligned}
$$

## Restrict the model

$$
\boldsymbol{\Lambda} \boldsymbol{\Phi} \boldsymbol{\Lambda}^{\top}=\boldsymbol{\Lambda}_{2} \mathbf{I} \boldsymbol{\Lambda}_{2}^{\top}
$$

- Set Phi = the identity, $\operatorname{socov}(\mathbf{F})=1$
- All the factors are standardized, as well as independent.
- Justify this on the grounds of simplicity.
- Say the factors are "orthogonal" (at right angles, uncorrelated).


## Another Source of non-identifiability

 $R$ is an orthoganal (rotation) matrix$$
\begin{aligned}
\boldsymbol{\Sigma} & =\boldsymbol{\Lambda} \boldsymbol{\Lambda}^{\top}+\boldsymbol{\Omega} \\
& =\boldsymbol{\Lambda} \mathbf{R R}^{\top} \boldsymbol{\Lambda}^{\top}+\boldsymbol{\Omega} \\
& =(\boldsymbol{\Lambda} \mathbf{R})\left(\mathbf{R}^{\top} \boldsymbol{\Lambda}^{\top}\right)+\boldsymbol{\Omega} \\
& =(\boldsymbol{\Lambda} \mathbf{R})(\boldsymbol{\Lambda} \mathbf{R})^{\top}+\boldsymbol{\Omega} \\
& =\boldsymbol{\Lambda}_{2} \boldsymbol{\Lambda}_{2}^{\top}+\boldsymbol{\Omega}
\end{aligned}
$$

Infinitely many rotation matrices produce the same Sigma.

## A Solution

- Place some restrictions on the factor loadings, so that the only rotation matrix that preserves the restrictions is the identity matrix. For example, $\lambda_{i j}=0$ for $\mathrm{j}>\mathrm{i}$
- There are other sets of restrictions that work.
- Generally, they result in a set of factor loadings that are impossible to interpret. Don't worry about it.
- Estimate the loadings by maximum likelihood. Other methods are possible but used much less than in the past.
- All (orthoganal) rotations result in the same value of the likelihood function (the maximum is not unique).
- Rotate the factors (that is, post-multiply the estimated loadings by a rotation matrix) so as to achieve a simple pattern that is easy to interpret.
- The result is often satisfying, but has no necessary connection to reality.


## Consulting advice

- When a non-statistician claims to have done a "factor analysis," ask what kind.
- Usually it was a principal components analysis.
- Principal components are linear combinations of the observed variables. They come from the observed variables by direct calculation.
- In true factor analysis, it's the observed variables that arise from the factors.
- So principal components analysis is kind of like backwards factor analysis, though the spirit is similar.
- Most factor analysis software (SAS, SPSS, etc.) does principal components analysis by default.


## Copyright Information

This slide show was prepared by Jerry Brunner, Department of Statistics, University of Toronto. It is licensed under a Creative Commons Attribution - ShareAlike 3.0 Unported License. Use any part of it as you like and share the result freely. These Powerpoint slides are available from the course website:
http://www.utstat.toronto.edu/brunner/oldclass/2053f22

