Figure 1. Traditional bifactor model with one general factor (G), three specific factors (S_k) and three observed variables Y_{ik} per domain. ε_{ik}: error variables, λ_{Gik}: G-factor loadings, λ_{Sik}: specific factor loadings $k = 1, \ldots, K$; K: number of domains; $i = 1, \ldots, I_k$; I_k: number of indicators i belonging to domain k. For simplicity, not all parameters and variables are labeled.