STA2212: Inference and Likelihood

A. Notation

One random variable: Given a model for X which assumes X has a density $f(x; \theta)$, $\theta \in \Theta \subset \mathbb{R}^k$, we have the following definitions:

| likelihood function | $L(\theta; x) = c(x)f(x; \theta)$ | $\mathcal{L}(heta)$ |
|---|---|---|
| log-likelihood function | $\ell(\theta; x) = \log L(\theta; x) = \log f$ | $(x;\theta) + a(x)$ |
| score function | $u(\theta) = \partial \ell(\theta; x) / \partial \theta$ | $\ell'(x;\theta)$ |
| observed information function | $j(\theta) = -\partial^2 \ell(\theta; x) / \partial \theta \partial \theta^T$ | $J(\theta) = \mathcal{E}_{\theta}\{j(\theta)\}$ |
| expected information (in one observation) | $i(\theta) = \mathcal{E}_{\theta} \{ U(\theta) U(\theta)^T \}^1$ | $I(\theta)$ (p.245) |

Independent observations: When we have X_i independent, identically distributed from $f(x_i; \theta)$, then, denoting the observed sample $\boldsymbol{x} = (x_1, \ldots, x_n)$ we have:

| likelihood function | $L(\theta; \boldsymbol{x}) = \prod_{i=1}^{n} f(x_i; \theta)$ | $\mathcal{L}(heta)$ |
|-------------------------------|--|--|
| log-likelihood function | $\ell(\theta) = \ell(\theta; \boldsymbol{x}) = \sum_{i=1}^{n} \ell(\theta; x_i)$ | $\ell(heta)$ |
| maximum likelihood estimate | | $S(\boldsymbol{X})$ |
| score function | $U(\theta) = \ell'(\theta) = \sum U_i(\theta)$ | $\boldsymbol{S}(\theta)$ (p.273) |
| observed information function | $j(heta) = -\ell''(heta) = -\ell''(heta; oldsymbol{x})$ | $nJ(\theta) = \mathcal{E}_{\theta}\{-\ell''(x;\theta)\}$ |
| observed (Fisher) information | $j(\hat{	heta})$ | $n \widehat{I}(\theta)$ (p.254) |
| expected (Fisher) information | $i(\theta) = \mathcal{E}_{\theta} \{ U(\theta) U(\theta)^T \} = n i_1(\theta)$ | $I_n(\theta) = nI(\theta)$ |

Comments:

- 1. the maximum likelihood estimate $\hat{\theta}_n$ is usually obtained by solving the *score* equation $\ell'(\theta; \mathbf{x}) = 0$. Lazy notation is $\hat{\theta}$, but for asymptotics $\hat{\theta}_n$ is preferred.
- 2. It doesn't really matter for the definitions above if the observations are independent and identically distributed (i.i.d.), or only independent, but the theorems that are proved in MS Ch. 5 and AoS Ch. 9 assume i.i.d..
- 3. There are important distinctions to be careful about in the notation for likelihood and its quantities:
 - (a) Are we working with a single observation x, X or n observations x, X?
 - (b) Do we want to find the distribution of something; so $\ell(\theta; X)$ or calculate data summaries; $\ell(\theta; x)$?

 ${}^{1}U(\theta) = u(\theta; X)$

B. First order asymptotic theory MS §5.4

1. θ is a scalar

If the components of X are i.i.d., then the score function $U(\theta; X)$ is a sum of i.i.d. random variables, and we can show that it has expected value 0 and variance $I_n(\theta)$ (or $i(\theta)$ in my notation). Under some regularity conditions on the density $f(x_i; \theta)$ (MS A1-A6, p.245), the central limit theorem gives

$$\frac{U(\theta)}{I_n^{1/2}(\theta)} \xrightarrow{d} N(0,1), \text{ equivalently } \frac{1}{\sqrt{n}} U(\theta) \xrightarrow{d} N\{0, I(\theta)\}.$$
(1)

Almost everything else follows from this result and Slutsky's theorem. For example, we can show that

$$(\hat{\theta} - \theta)I_n^{1/2}(\theta) = U(\theta)/I_n^{1/2}(\theta) + o_p(1),$$

where $o_p(1)$ means a remainder term that goes to 0 in probability as $n \to \infty$, so we have the second result

$$(\hat{\theta} - \theta) I_n^{1/2}(\theta) \stackrel{d}{\to} N(0, 1).$$
(2)

These limit theorems give us two corresponding approximations to use with n fixed:

$$U(\theta) \sim N(0, I_n(\theta)), \qquad (3)$$

and

$$\hat{\theta} - \theta \sim N\left(0, 1/I_n(\theta)\right). \tag{4}$$

The notation \sim is read as "is approximately distributed as".

The proof of MS Theorem 5.3 allows that $I(\theta) = \operatorname{var}\{\ell'(\theta; X_i)\}$ and $J(\theta) = E\{-\ell''(\theta); X_i\}$ might be different, which is handy later for the study of misspecified models.

Having the unknown quantity θ in the variance in (3) and (4) is inconvenient, but to the same order of approximation, we can replace $I_n(\theta)$ by $I_n(\hat{\theta})$ or by $j(\hat{\theta})$; the latter is denoted $\widehat{I_n(\theta)}$ in MS, p. 254. In AoS, $I_n^{-1/2}(\theta)$ is called **se** and $I_n^{-1/2}(\hat{\theta})$ is called **se**, but the use of $j(\hat{\theta}) = -\ell''(\hat{\theta}; \boldsymbol{x})$ is not mentioned.