

Sample Space Ω , $\omega \in \Omega$

- Observing whether a single individual is male or female:

$$\Omega = \{F, M\}$$

- Pair of individuals: observe their genders in order:

$$\Omega = \{(F, F), (F, M), (M, F), (M, M)\}$$

- Select n people and count the number of females:

$$\Omega = \{0, \dots, n\}$$

- For limits problems, the points in Ω are infinite sequences

Random variables are functions
from Ω into the set of real numbers

$$Pr\{X \in B\} = Pr(\{\omega \in \Omega : X(\omega) \in B\})$$

Random sample $X_1(\omega), \dots, X_n(\omega)$

$$T = T(X_1, \dots, X_n)$$

$$T = T_n(\omega)$$

Let $n \rightarrow \infty$

To see what happens for large samples

Modes of Convergence

- Almost Sure Convergence
- Convergence in Probability
- Convergence in Distribution

Almost Sure Convergence

We say that T_n converges *almost surely* to T , and write $T_n \xrightarrow{a.s.}$ if

$$\Pr\{\omega : \lim_{n \rightarrow \infty} T_n(\omega) = T(\omega)\} = 1.$$

Acts like an ordinary limit, except possibly on a set of probability zero.

All the usual rules apply.

Strong Law of Large Numbers

$$\overline{X}_n \xrightarrow{a.s.} E(X_i) = \mu$$

The only condition required for this to hold is the existence of the expected value.

Probability is long run relative frequency

- Statistical experiment: Probability of “success” is p
- Carry out the experiment many times independently.
- Code the results $X_i=1$ if success, $X_i=0$ for failure, $i = 1, 2, \dots$

$$\begin{aligned} E(X_i) &= \sum_{x_i} x_i Pr\{X_1 = x_i\} \\ &= 0 \cdot (1 - p) + 1 \cdot p \\ &= p \end{aligned}$$

Relative frequency is

$$\frac{1}{n} \sum_{i=1}^n X_i = \bar{X}_n \xrightarrow{a.s.} p$$

Simulation

- Weather model
- Performance of statistical methods
- Estimate almost any probability that's hard to figure out
- Confidence intervals for the estimate

A hard elementary problem

- Roll a fair die 13 times and observe the number each time.
- What is the probability that the sum of the numbers is divisible by 3?

```
> die = c(1,1,1,1,1,1)/6; die
[1] 0.1666667 0.1666667 0.1666667 0.1666667 0.1666667 0.1666667
> rmultinom(1,1,die)
      [,1]
[1,]    0
[2,]    0
[3,]    1
[4,]    0
[5,]    0
[6,]    0
> rmultinom(1,13,die)
      [,1]
[1,]    5
[2,]    2
[3,]    1
[4,]    2
[5,]    2
[6,]    1
```

```
> tot = sum(rmultinom(1,13,die)*(1:6))
> tot
[1] 42
> tot/3 == floor(tot/3)
[1] TRUE
> 42/3
[1] 14
```

Estimated Probability

```
> nsim = 1000 # nsim is the Monte Carlo sample size
> set.seed(9999) # So I can reproduce the numbers if desired.
> kount = numeric(nsim)
> for(i in 1:nsim)
+   {
+     tot = sum(rmultinom(1,13,die)*(1:6))
+     kount[i] = (tot/3 == floor(tot/3))
+     # Logical will be converted to numeric
+   }

> kount[1:20]
[1] 0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 1 0

> xbar = mean(kount); xbar
[1] 0.329
```

Confidence Interval

```
> z = qnorm(0.995); z
```

```
[1] 2.575829
```

```
> pnorm(z)-pnorm(-z) # Just to check
```

```
[1] 0.99
```

```
> margerror99 = sqrt(xbar*(1-xbar)/nsim)*z; margerror99
```

```
[1] 0.03827157
```

```
> cat("Estimated probability is ",xbar," with 99% margin of error ",  
+     margerror99,"\n")
```

```
Estimated probability is 0.329 with 99% margin of error 0.03827157
```

```
> cat("99% Confidence interval from ",xbar-margerror99," to ",  
+     xbar+margerror99,"\n")
```

```
99% Confidence interval from 0.2907284 to 0.3672716
```

Recall the Change of Variables
formula: Let $Y = g(X)$

$$E(Y) = \int_{-\infty}^{\infty} y f_Y(y) dy = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

Or, for discrete random variables

$$E(Y) = \sum_y y p_Y(y) = \sum_x g(x) p_X(x)$$

Let X_1, \dots, X_n be independent and identically distributed random variables; let X be a general random variable from this same distribution, and $Y=g(X)$

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n g(X_i) &= \frac{1}{n} \sum_{i=1}^n Y_i \xrightarrow{a.s.} E(Y) \\ &= E(g(X)) \end{aligned}$$

So for example

$$\frac{1}{n} \sum_{i=1}^n X_i^k \xrightarrow{a.s.} E(X^k)$$

$$\frac{1}{n} \sum_{i=1}^n U_i^2 V_i W_i^3 \xrightarrow{a.s.} E(U^2 V W^3)$$

That is, sample moments converge almost surely to population moments.

Convergence in Probability

We say that T_n converges *in probability* to T , and write $T_n \xrightarrow{P} T$ if for all $\epsilon > 0$,

$$\lim_{n \rightarrow \infty} P\{|T_n - T| < \epsilon\} = 1$$

- Convergence in probability (say to a constant θ) means no matter how small the interval around θ , for large enough n ($n > N_1$) the probability of getting that close to θ is as close to one as you like.
- Almost sure convergence means no matter how small the interval around θ , for large enough n ($n > N_2$) the probability of getting that close to θ equals one.
- Almost Sure Convergence \Rightarrow Convergence in Probability
- Strong Law of Large Numbers \Rightarrow Weak Law of Large Numbers

Convergence in Distribution

Denote the cumulative distribution functions of T_1, T_2, \dots by $F_1(t), F_2(t), \dots$ respectively, and denote the cumulative distribution function of T by $F(t)$.

We say that T_n converges *in distribution* to T , and write $T_n \xrightarrow{d} T$ if for every point t at which F is continuous,

$$\lim_{n \rightarrow \infty} F_n(t) = F(t)$$

Univariate Central Limit Theorem says

$$Z_n = \frac{\sqrt{n}(\bar{X}_n - \mu)}{\sigma} \xrightarrow{d} Z \sim N(0, 1)$$

Connections among the Modes of Convergence

- $T_n \xrightarrow{a.s.} T \Rightarrow T_n \xrightarrow{P} T \Rightarrow T_n \xrightarrow{d} T.$
- If a is a constant, $T_n \xrightarrow{d} a \Rightarrow T_n \xrightarrow{P} a.$

Consistency

$T_n = T_n(X_1, \dots, X_n)$ is a statistic estimating a parameter θ

The statistic T_n is said to be *consistent* for θ if $T_n \xrightarrow{P} \theta$.

$$\lim_{n \rightarrow \infty} P\{|T_n - \theta| < \epsilon\} = 1$$

The statistic T_n is said to be *strongly consistent* for θ if $T_n \xrightarrow{a.s.} \theta$.

Strong consistency implies ordinary consistency.

Consistency of the Sample Variance

$$\begin{aligned}\hat{\sigma}_n^2 &= \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2 \\ &= \frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2\end{aligned}$$

By SLLN, $\bar{X}_n \xrightarrow{a.s.} \mu$ and $\frac{1}{n} \sum_{i=1}^n X_i^2 \xrightarrow{a.s.} E(X^2) = \sigma^2 + \mu^2$

Because the function $g(x, y) = x - y^2$ is continuous,

$$\hat{\sigma}_n^2 = g\left(\frac{1}{n} \sum_{i=1}^n X_i^2, \bar{X}_n\right) \xrightarrow{a.s.} g(\sigma^2 + \mu^2, \mu) = \sigma^2 + \mu^2 - \mu^2 = \sigma^2$$

Convergence of Random Vectors

1. Definitions (All quantities in boldface are vectors in \mathbb{R}^m unless otherwise stated)
 - ★ $\mathbf{T}_n \xrightarrow{a.s.} \mathbf{T}$ means $P\{\omega : \lim_{n \rightarrow \infty} \mathbf{T}_n(\omega) = \mathbf{T}(\omega)\} = 1$.
 - ★ $\mathbf{T}_n \xrightarrow{P} \mathbf{T}$ means $\forall \epsilon > 0, \lim_{n \rightarrow \infty} P\{\|\mathbf{T}_n - \mathbf{T}\| < \epsilon\} = 1$.
 - ★ $\mathbf{T}_n \xrightarrow{d} \mathbf{T}$ means for every continuity point \mathbf{t} of $F_{\mathbf{T}}$, $\lim_{n \rightarrow \infty} F_{\mathbf{T}_n}(\mathbf{t}) = F_{\mathbf{T}}(\mathbf{t})$.
2. $\mathbf{T}_n \xrightarrow{a.s.} \mathbf{T} \Rightarrow \mathbf{T}_n \xrightarrow{P} \mathbf{T} \Rightarrow \mathbf{T}_n \xrightarrow{d} \mathbf{T}$.
3. If \mathbf{a} is a vector of constants, $\mathbf{T}_n \xrightarrow{d} \mathbf{a} \Rightarrow \mathbf{T}_n \xrightarrow{P} \mathbf{a}$.
4. Strong Law of Large Numbers (SLLN): Let $\mathbf{X}_1, \dots, \mathbf{X}_n$ be independent and identically distributed random vectors with finite first moment, and let \mathbf{X} be a general random vector from the same distribution. Then $\bar{\mathbf{X}}_n \xrightarrow{a.s.} E(\mathbf{X})$.
5. Central Limit Theorem: Let $\mathbf{X}_1, \dots, \mathbf{X}_n$ be i.i.d. random vectors with expected value vector $\boldsymbol{\mu}$ and covariance matrix $\boldsymbol{\Sigma}$. Then $\sqrt{n}(\bar{\mathbf{X}}_n - \boldsymbol{\mu})$ converges in distribution to a multivariate normal with mean $\mathbf{0}$ and covariance matrix $\boldsymbol{\Sigma}$.

6. Slutsky Theorems for Convergence in Distribution:

- (a) If $\mathbf{T}_n \in \mathbb{R}^m$, $\mathbf{T}_n \xrightarrow{d} \mathbf{T}$ and if $f : \mathbb{R}^m \rightarrow \mathbb{R}^q$ (where $q \leq m$) is continuous except possibly on a set C with $P(\mathbf{T} \in C) = 0$, then $f(\mathbf{T}_n) \xrightarrow{d} f(\mathbf{T})$.
- (b) If $\mathbf{T}_n \xrightarrow{d} \mathbf{T}$ and $(\mathbf{T}_n - \mathbf{Y}_n) \xrightarrow{P} 0$, then $\mathbf{Y}_n \xrightarrow{d} \mathbf{T}$.
- (c) If $\mathbf{T}_n \in \mathbb{R}^d$, $\mathbf{Y}_n \in \mathbb{R}^k$, $\mathbf{T}_n \xrightarrow{d} \mathbf{T}$ and $\mathbf{Y}_n \xrightarrow{d} \mathbf{c}$, then

$$\begin{pmatrix} \mathbf{T}_n \\ \mathbf{Y}_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} \mathbf{T} \\ \mathbf{c} \end{pmatrix}$$

7. Slutsky Theorems for Convergence in Probability:

- (a) If $\mathbf{T}_n \in \mathbb{R}^m$, $\mathbf{T}_n \xrightarrow{P} \mathbf{T}$ and if $f : \mathbb{R}^m \rightarrow \mathbb{R}^q$ (where $q \leq m$) is continuous except possibly on a set C with $P(\mathbf{T} \in C) = 0$, then $f(\mathbf{T}_n) \xrightarrow{P} f(\mathbf{T})$.
- (b) If $\mathbf{T}_n \xrightarrow{P} \mathbf{T}$ and $(\mathbf{T}_n - \mathbf{Y}_n) \xrightarrow{P} 0$, then $\mathbf{Y}_n \xrightarrow{P} \mathbf{T}$.
- (c) If $\mathbf{T}_n \in \mathbb{R}^d$, $\mathbf{Y}_n \in \mathbb{R}^k$, $\mathbf{T}_n \xrightarrow{P} \mathbf{T}$ and $\mathbf{Y}_n \xrightarrow{P} \mathbf{Y}$, then

$$\begin{pmatrix} \mathbf{T}_n \\ \mathbf{Y}_n \end{pmatrix} \xrightarrow{P} \begin{pmatrix} \mathbf{T} \\ \mathbf{Y} \end{pmatrix}$$

8. Delta Method (Theorem of Cramér, Ferguson p. 45): Let $g : \mathbb{R}^d \rightarrow \mathbb{R}^k$ be such that the elements of $\dot{g}(\mathbf{x}) = \left[\frac{\partial g_i}{\partial x_j} \right]_{k \times d}$ are continuous in a neighborhood of $\boldsymbol{\theta} \in \mathbb{R}^d$. If \mathbf{T}_n is a sequence of d -dimensional random vectors such that $\sqrt{n}(\mathbf{T}_n - \boldsymbol{\theta}) \xrightarrow{d} \mathbf{T}$, then $\sqrt{n}(g(\mathbf{T}_n) - g(\boldsymbol{\theta})) \xrightarrow{d} \dot{g}(\boldsymbol{\theta})\mathbf{T}$. In particular, if $\sqrt{n}(\mathbf{T}_n - \boldsymbol{\theta}) \xrightarrow{d} \mathbf{T} \sim N(\mathbf{0}, \boldsymbol{\Sigma})$, then $\sqrt{n}(g(\mathbf{T}_n) - g(\boldsymbol{\theta})) \xrightarrow{d} \mathbf{Y} \sim N(\mathbf{0}, \dot{g}(\boldsymbol{\theta})\boldsymbol{\Sigma}\dot{g}(\boldsymbol{\theta})')$.

An application of the Slutsky Theorems

Let $X_1, \dots, X_n \stackrel{i.i.d.}{\sim} ?(\mu, \sigma^2)$

By CLT, $Y_n = \sqrt{n}(\bar{X}_n - \mu) \xrightarrow{d} Y \sim N(0, \sigma^2)$

Let $\hat{\sigma}_n$ be *any* consistent estimator of σ .

Then by 6c, $\mathbf{T}_n = \begin{pmatrix} Y_n \\ \hat{\sigma}_n \end{pmatrix} \xrightarrow{d} \begin{pmatrix} Y \\ \sigma \end{pmatrix} = \mathbf{T}$

The function $f(x, y) = x/y$ is continuous except if $y = 0$
so by 6a,

$$f(\mathbf{T}_n) = \frac{\sqrt{n}(\bar{X}_n - \mu)}{\hat{\sigma}_n} \xrightarrow{d} f(\mathbf{T}) = \frac{Y}{\sigma} \sim N(0, 1)$$

Because

- The multivariate CLT establishes convergence to a multivariate normal, and
- Vectors of MLEs are approximately normal for large samples
- We need to look at random vectors and the multivariate normal distribution.