

Covariance Structure Approach to Within-cases

Using SAS proc mixed

Advantages

- Straightforward: It's familiar univariate regression
- Just MSE is different, because of correlated observations
- Nicer treatment of missing data (valid if missing at random)
- Can have time-varying covariates
- Flexible modeling of non-independence within cases
- Can accommodate more factor levels than cases (with assumptions)

Usual covariance matrix of

Y_1, \dots, Y_n

$$\begin{bmatrix} \sigma^2 & 0 & 0 & \dots & 0 & 0 \\ 0 & \sigma^2 & 0 & \dots & 0 & 0 \\ 0 & 0 & \sigma^2 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & 0 \\ 0 & 0 & 0 & \dots & \sigma^2 & 0 \\ 0 & 0 & 0 & \dots & 0 & \sigma^2 \end{bmatrix}$$

In the covariance structure approach

- There are n “subjects.”
- There are k (“repeated”) measurements per subject
- There are nk cases: n blocks of k rows
- Data are multivariate normal (dimension nk)
- Familiar regression model for the vector of means
- Special structure for the variance-covariance matrix: not just a diagonal matrix with σ^2 on the main diagonal

Structure of the variance-covariance matrix

- Covariance matrix of the data has a **block diagonal** structure: $n \times n$ matrix of little $k \times k$ variance-covariance matrices (partitioned matrix)
- Off diagonal matrices are all zeros -- no correlation between data from different cases
- Matrices on the main diagonal are all the same (equal variance assumption)

Block Diagonal Covariance Matrix

$$\begin{bmatrix} \Sigma & \mathbf{0} & \dots & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \Sigma & \dots & \mathbf{0} & \mathbf{0} \\ \vdots & \vdots & \ddots & \vdots & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \dots & \Sigma & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \dots & \mathbf{0} & \Sigma \end{bmatrix}$$

Σ is the matrix of variances and covariances of the data from a single subject.

Σ may have different *structures*

- May be unknown

$$\Sigma = \begin{bmatrix} \sigma_1^2 & \sigma_{1,2} & \sigma_{1,3} & \sigma_{1,4} \\ \sigma_{2,1} & \sigma_2^2 & \sigma_{2,3} & \sigma_{2,4} \\ \sigma_{3,1} & \sigma_{3,2} & \sigma_3^2 & \sigma_{3,4} \\ \sigma_{4,1} & \sigma_{4,2} & \sigma_{4,3} & \sigma_4^2 \end{bmatrix} = \begin{bmatrix} \sigma_1^2 & \sigma_{1,2} & \sigma_{1,3} & \sigma_{1,4} \\ & \sigma_2^2 & \sigma_{2,3} & \sigma_{2,4} \\ & & \sigma_3^2 & \sigma_{3,4} \\ & & & \sigma_4^2 \end{bmatrix}$$

- May be something else

Compound Symmetry

- Why are data from the same case correlated?
- Because each case makes its own contribution -- add a (random) quantity that is different for each case
- Some monkeys are just better at solving puzzles

Model for Case i in Within-Cases Condition j

$Y_{ij} = \beta_0 + \beta_1 x_{ij1} + \beta_2 x_{ij2} + \cdots + \beta_{p-1} x_{ij(p-1)} + \delta_i + \epsilon_{ij}$, where

- Everything is independent for $i = 1, \dots, n$
- ϵ_{ij} and δ_i are independent
- $\epsilon_{ij} \sim N(0, \sigma^2)$ and $\delta_i \sim N(0, \sigma_\delta^2)$
- ϵ_{ij} and $\epsilon_{i\ell}$ are independent for $j \neq \ell$

This implies

- $Var(Y_{ij}) = \sigma_\delta^2 + \sigma^2$
- $Cov(Y_{ij}, Y_{i\ell}) = \sigma_\delta^2$ for $j \neq \ell$

Compound Symmetry

$$\Sigma = \begin{bmatrix} \sigma^2 + \sigma_1 & \sigma_1 & \sigma_1 & \sigma_1 \\ \sigma_1 & \sigma^2 + \sigma_1 & \sigma_1 & \sigma_1 \\ \sigma_1 & \sigma_1 & \sigma^2 + \sigma_1 & \sigma_1 \\ \sigma_1 & \sigma_1 & \sigma_1 & \sigma^2 + \sigma_1 \end{bmatrix}$$

Fewer parameters to estimate

Available covariance structures include

- Unknown: type=un
- Compound symmetry: type=cs
- Variance components: type=vc
- First-order autoregressive: type=ar(1)
- Spatial autocorrelation: covariance is a function of Euclidian distance
- Factor analysis
- Many others

Why not always assume covariance structure unknown?

- No reason why not, if you have enough data.
- When number of unknown parameters is large relative to sample size, variances of estimators are large => confidence intervals wide, tests weak.
- In some studies, there can be more treatment conditions than cases, and unique estimates of parameters don't even exist.
- There is always a tradeoff between assumptions and amount of data.

First-order autoregressive time series

$$\Sigma = \sigma^2 \begin{bmatrix} 1 & \rho & \rho^2 & \rho^3 \\ \rho & 1 & \rho & \rho^2 \\ \rho^2 & \rho & 1 & \rho \\ \rho^3 & \rho^2 & \rho & 1 \end{bmatrix}$$

- Usually much bigger matrix
- Could have a handful of cases measured at hundreds of time points
- Or even just one “case,” say a company

Eating Norm Study

- Two free meals at the psych lab
- One with another student, one alone
- But it's not really another student. It's a "confederate."
- Confederate either eats a lot or a little.
- Dine with the confederate first, or second.
- DV is how much you eat. They weigh it.
- Covariates: How long since you ate, and how hungry you are. It can be different each time.

Variables

- Amount subject eats: DV
- Amount confederate eats (between)
- Eat alone or with confederate (within)
- Eat with confederate first, or second (between)
- Reported time since ate (covariate)
- Reported hunger (covariate)

- Notice these are **time-varying covariates**

Just can't do it with the multivariate approach

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_k \end{bmatrix} = \begin{bmatrix} E[Y_1|\mathbf{X}=\mathbf{x}] \\ E[Y_2|\mathbf{X}=\mathbf{x}] \\ \vdots \\ E[Y_k|\mathbf{X}=\mathbf{x}] \end{bmatrix} = \begin{bmatrix} \beta_{0,1} + \beta_{1,1}x_1 + \cdots + \beta_{p-1,1}x_{p-1} \\ \beta_{0,2} + \beta_{1,2}x_1 + \cdots + \beta_{p-1,2}x_{p-1} \\ \vdots \\ \beta_{0,k} + \beta_{1,k}x_1 + \cdots + \beta_{p-1,k}x_{p-1} \end{bmatrix}$$