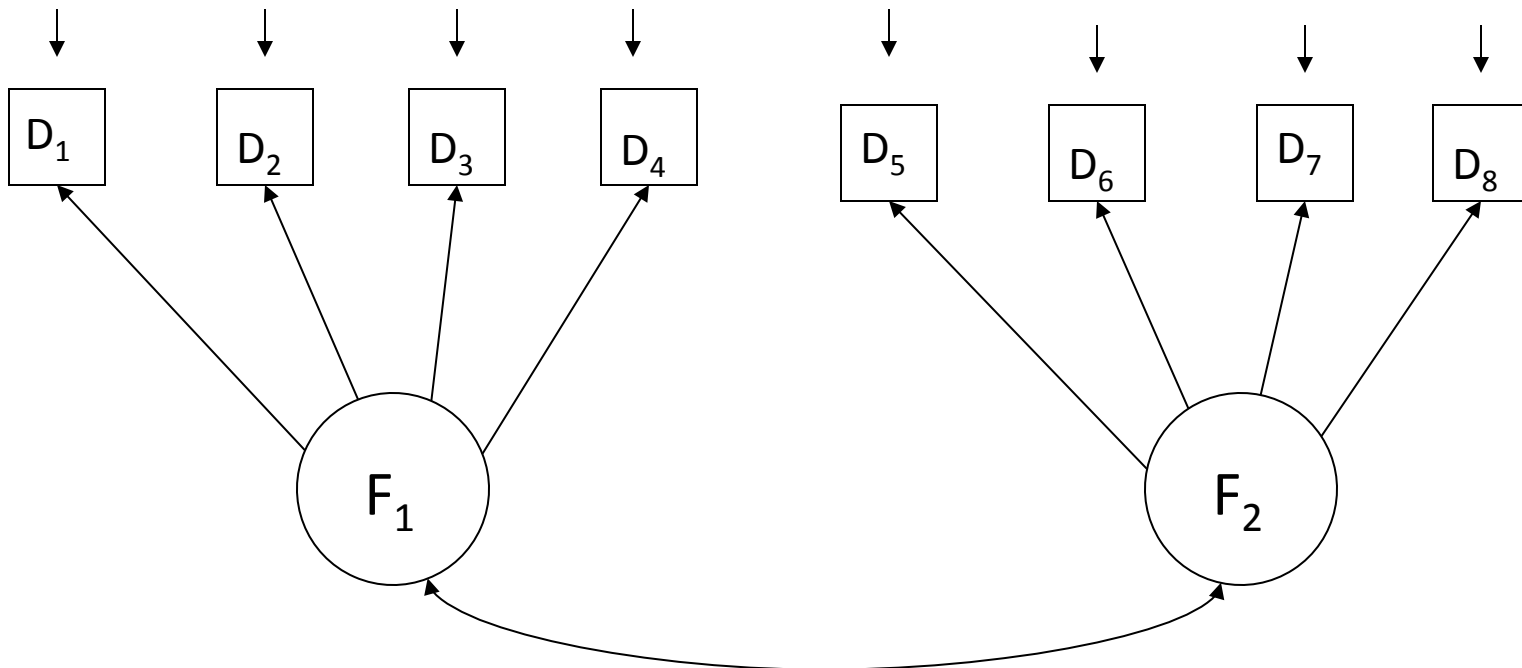


Factor Analysis

The Measurement Model

Factor Analysis: The Measurement Model

$$\mathbf{D}_i = \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i$$



Example with 2 factors and 8 observed variables

$$\mathbf{D}_i = \mathbf{\Lambda} \mathbf{F}_i + \mathbf{e}_i$$

$$\begin{bmatrix} D_{i,1} \\ D_{i,2} \\ D_{i,3} \\ D_{i,4} \\ D_{i,5} \\ D_{i,6} \\ D_{i,7} \\ D_{i,8} \end{bmatrix} = \begin{bmatrix} \lambda_{11} & \lambda_{12} \\ \lambda_{21} & \lambda_{22} \\ \lambda_{31} & \lambda_{32} \\ \lambda_{41} & \lambda_{42} \\ \lambda_{51} & \lambda_{52} \\ \lambda_{61} & \lambda_{62} \\ \lambda_{71} & \lambda_{27} \\ \lambda_{81} & \lambda_{82} \end{bmatrix} \begin{bmatrix} F_{i,1} \\ F_{i,2} \end{bmatrix} + \begin{bmatrix} e_{i,1} \\ e_{i,2} \\ e_{i,3} \\ e_{i,4} \\ e_{i,5} \\ e_{i,6} \\ e_{i,7} \\ e_{i,8} \end{bmatrix}$$

$$D_{i,1} = \lambda_{11}F_{i,1} + \lambda_{12}F_{i,2} + e_{i,1}$$

$$D_{i,2} = \lambda_{21}F_{i,1} + \lambda_{22}F_{i,2} + e_{i,2} \text{ etc.}$$

The lambda values are called **factor loadings**.

Terminology

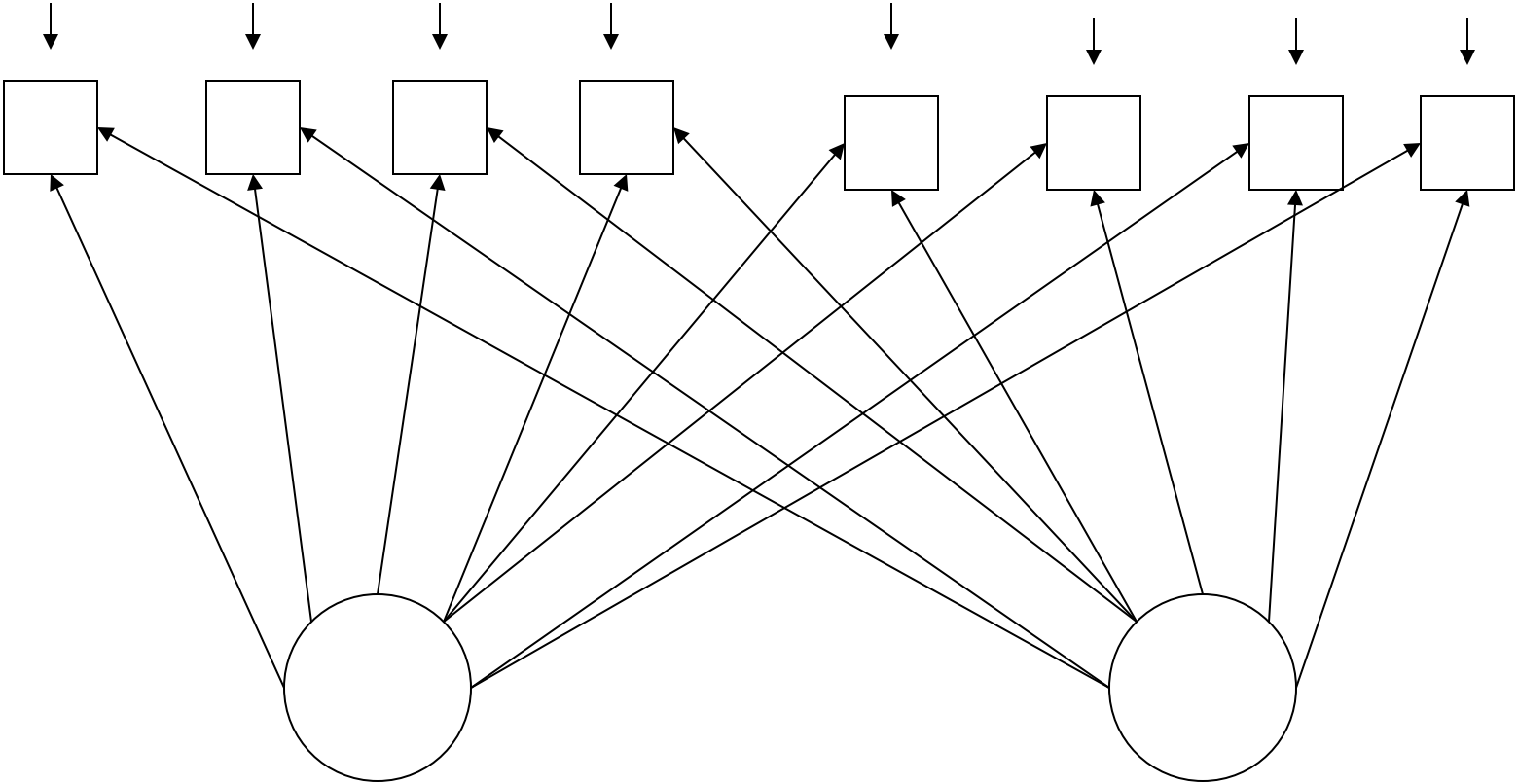
$$D_{i,1} = \lambda_{11}F_{i,1} + \lambda_{12}F_{i,2} + e_{i,1}$$
$$D_{i,2} = \lambda_{21}F_{i,1} + \lambda_{22}F_{i,2} + e_{i,2} \text{ etc.}$$

- The lambda values are called **factor loadings**.
- F_1 and F_2 are sometimes called **common factors**, because they influence all the observed variables.
- e_1, \dots, e_8 sometimes called **unique factors**, because each one influences only a single observed variable.

Factor Analysis can be

- **Exploratory:** The goal is to describe and summarize the data by explaining a large number of observed variables in terms of a smaller number of latent variables (factors). The factors are the reason the observable variables have the correlations they do.
- **Confirmatory:** Statistical estimation and testing as usual

Part One: Unconstrained (Exploratory) Factor Analysis



$$\mathbf{D} = \mathbf{\Lambda}\mathbf{F} + \mathbf{e}$$

$$V(\mathbf{F}) = \mathbf{\Phi}$$

$$V(\mathbf{e}) = \mathbf{\Omega} \text{ (usually diagonal)}$$

\mathbf{F} and \mathbf{e} independent multivariate normal

$$V(\mathbf{D}) = \mathbf{\Sigma} = \mathbf{\Lambda}\mathbf{\Phi}\mathbf{\Lambda}' + \mathbf{\Omega}$$

Main interest is in the number of factors and the factor loadings $\mathbf{\Lambda}$.

A Re-parameterization

$$\Sigma = \Lambda \Phi \Lambda' + \Omega$$

Write $\Phi = \mathbf{S}\mathbf{S}'$ (square root matrix), so

$$\begin{aligned}\Lambda \Phi \Lambda' &= \Lambda \mathbf{S}\mathbf{S}' \Lambda' \\ &= (\Lambda \mathbf{S}) \mathbf{I} (\mathbf{S}' \Lambda') \\ &= (\Lambda \mathbf{S}) \mathbf{I} (\Lambda \mathbf{S})' \\ &= \Lambda_2 \mathbf{I} \Lambda_2'\end{aligned}$$

Parameters are not identifiable

$$\Sigma = \Lambda \Phi \Lambda' + \Omega \quad \Lambda \Phi \Lambda' = \Lambda_2 \mathbf{I} \Lambda_2'$$

- Phi could be *any* symmetric positive definite matrix and this would work.
- Infinitely many (Lambda, Phi) pairs give the same Sigma, and hence the same distribution of the data.
- Phi is completely arbitrary (so is Lambda)
- This shows that the parameters of the general measurement model are not identifiable without some restrictions on the possible values of the parameter matrices.
- Notice that the general unrestricted model could be very close to the truth. But the parameters cannot be estimated successfully, period.

Restrict the model

$$\Lambda \Phi \Lambda' = \Lambda_2 \mathbf{I} \Lambda_2'$$

- Set $\Phi = \mathbf{I}$, so $V(F) = \mathbf{I}$
- Justify this on the grounds of simplicity.
- Say the factors are “orthogonal” (at right angles, uncorrelated).

Standardize the observed variables

- For $j = 1, \dots, k$ and independently for $i=1, \dots, n$

- $$Z_{ij} = \frac{D_{ij} - \bar{D}_j}{s_j}$$

- Assume each observed variable has variance one as well as mean zero.
- Sigma is now a correlation matrix.

Revised Exploratory Factor Analysis Model

$$\mathbf{Z} = \mathbf{\Lambda}\mathbf{F} + \mathbf{e}$$

$$V(\mathbf{F}) = \mathbf{I}$$

$$V(\mathbf{e}) = \mathbf{\Omega} \text{ (usually diagonal)}$$

\mathbf{F} and \mathbf{e} independent multivariate normal

$$V(\mathbf{D}) = \mathbf{\Sigma} = \mathbf{\Lambda}\mathbf{\Lambda}' + \mathbf{\Omega}$$

Meaning of the factor loadings

$$\begin{aligned} \text{Corr}(X_6, F_2) &= \text{Cov}(X_6, F_2) = E(X_6 F_2) \\ &= E((\lambda_{61} F_1 + \lambda_{62} F_2) F_2) \\ &= \lambda_{61} E(F_1 F_2) + \lambda_{62} E(F_2^2) \\ &= \lambda_{61} E(F_1) E(F_2) + \lambda_{62} \text{Var}(F_2) \\ &= \lambda_{62} \end{aligned}$$

- λ_{ij} is the correlation between variable i and factor j .
- Square of λ_{ij} is the reliability of variable i as a measure of factor j .

Communality

$$\begin{aligned} \text{Var}(X_i) &= \sum_{j=1}^p \lambda_{ij} F_j + e_i \\ &= \sum_{j=1}^p \lambda_{ij}^2 \text{Var}(F_j) + \text{Var}(e_i) \\ &= \sum_{j=1}^p \lambda_{ij}^2 + \omega_i \end{aligned}$$

- $\sum_{j=1}^p \lambda_{ij}^2$ is the proportion of variance in variable i that comes from the common factors.
- It is called the **communality** of variable i .
- The communality cannot exceed one.
- $\text{Var}(\omega_i) = 1 - \sum_{j=1}^p \lambda_{ij}^2$ Peculiar?

If we could estimate the factor loadings

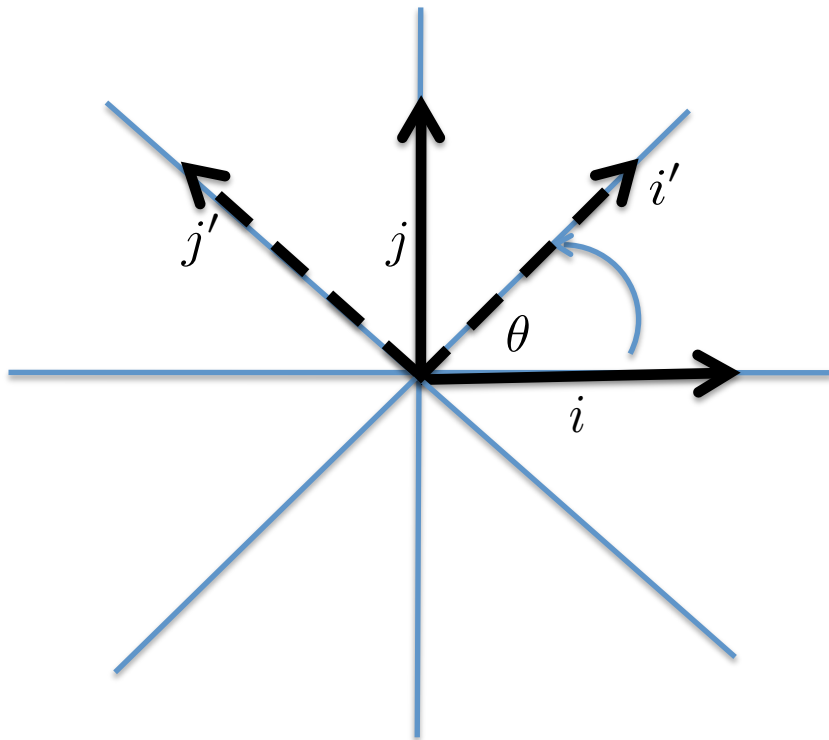
- We could estimate the correlation of each observable variable with each factor.
- We could easily estimate reliabilities.
- We could estimate how much of the variance in each observable variable comes from each factor.
- This could reveal what the underlying factors are, and what they mean.
- *Number* of common factors can be very important too.

Examples

- A major study of how people describe objects (using 7-point scales from Ugly to Beautiful, Strong to Weak, Fast to Slow etc. revealed 3 factors of connotative meaning:
 - Evaluation
 - Potency
 - Activity
- Factor analysis of a large collection of personality scales revealed 2 major factors:
 - Neuroticism
 - Extraversion
- Yet another study led to 16 personality factors, the basis of the widely used 16 pf test.

Rotation Matrices

- Have a co-ordinate system in terms of \vec{i}, \vec{j} orthonormal vectors
- Rotate the axes through an angle θ .



$$\begin{aligned} \vec{i}' &= \vec{i} \cos \theta + \vec{j} \sin \theta \\ \vec{j}' &= -\vec{i} \sin \theta + \vec{j} \cos \theta \end{aligned}$$

$$i' = (\cos \theta)i + (\sin \theta)j$$

$$j' = (-\sin \theta)i + (\cos \theta)j$$

$$\begin{bmatrix} i' \\ j' \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} i \\ j \end{bmatrix} = \mathbf{R} \begin{bmatrix} i \\ j \end{bmatrix}$$

$$\begin{aligned} \mathbf{R}\mathbf{R}' &= \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \\ &= \begin{bmatrix} \cos^2 \theta + \sin^2 \theta & -\cos \theta \sin \theta + \sin \theta \cos \theta \\ -\sin \theta \cos \theta + \cos \theta \sin \theta & \sin^2 \theta + \cos^2 \theta \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \mathbf{I} \end{aligned}$$

The transpose rotated the axes back through an angle of minus theta.

In General

- A $p \times p$ matrix \mathbf{R} satisfying $\mathbf{R}^{-1} = \mathbf{R}^T$ is called an *orthogonal matrix*.
- Geometrically, pre-multiplication by an orthogonal matrix corresponds to a rotation in p -dimensional space.
- If you think of a set of factors \mathbf{F} as a set of axes (underlying dimensions), then \mathbf{RF} is a *rotation* of the factors.
- Call it an *orthogonal* rotation, because the factors remain uncorrelated (at right angles).

Another Source of non-identifiability

$$\begin{aligned}\Sigma &= \Lambda\Lambda' + \Omega \\ &= \Lambda\mathbf{R}\mathbf{R}'\Lambda' + \Omega \\ &= (\Lambda\mathbf{R})(\mathbf{R}'\Lambda') + \Omega \\ &= (\Lambda\mathbf{R})(\Lambda\mathbf{R})' + \Omega \\ &= \Lambda_2\Lambda_2' + \Omega\end{aligned}$$

Infinitely many rotation matrices produce the same Sigma.

New Model

$$\begin{aligned}\mathbf{Z} &= \Lambda_2 \mathbf{F} + \mathbf{e} \\ &= (\Lambda \mathbf{R}) \mathbf{F} + \mathbf{e} \\ &= \Lambda (\mathbf{R} \mathbf{F}) + \mathbf{e} \\ &= \Lambda \mathbf{F}' + \mathbf{e}\end{aligned}$$

\mathbf{F}' is a set of *rotated* factors.

A Solution

- Place some restrictions on the factor loadings, so that the only rotation matrix that preserves the restrictions is the identity matrix. For example, $\lambda_{ij} = 0$ for $j > i$
- There are other sets of restrictions that work.
- Generally, they result in a set of factor loadings that are impossible to interpret. Don't worry about it.
- Estimate the loadings by maximum likelihood. Other methods are possible but used much less than in the past.
- All (orthogonal) rotations result in the same value of the likelihood function (the maximum is not unique).
- Rotate the factors (that is, multiply the loadings by a rotation matrix) so as to achieve a simple pattern that is easy to interpret.

Rotate the factor solution

- Rotate the factors to achieve a simple pattern that is easy to interpret.
- There are various criteria. They are all iterative, taking a number of steps to approach some criterion.
- The most popular rotation method is varimax rotation.
- Varimax rotation tries to maximize the (squared) loading of each observable variable with just one underlying factor.
- So typically each variable has a big loading on (correlation with) one of the factors, and small loadings on the rest.
- Look at the loadings and decide what the factors mean (name the factors).

A Warning

- When a non-statistician claims to have done a “factor analysis,” ask what kind.
- Usually it was a principal components analysis.
- Principal components are linear combinations of the observed variables. They come from the observed variables by direct calculation.
- In true factor analysis, it’s the observed variables that arise from the factors.
- So principal components analysis is kind of like backwards factor analysis, though the spirit is similar.
- Most factor analysis (SAS, SPSS, etc.) does principal components analysis by default.