

# More Linear Algebra<sup>1</sup>

STA 302: Fall 2017

---

<sup>1</sup>See Chapter 2 of *Linear models in statistics* for more detail. This slide show is an open-source document. See last slide for copyright information.

# Overview

- 1 Things you already know
- 2 Trace
- 3 Spectral decomposition
- 4 Positive definite
- 5 Square root matrices
- 6 Extras
- 7 R

# You already know about

- Matrices  $A = (a_{ij})$
- Column vectors  $\mathbf{v} = (v_j)$
- Matrix addition and subtraction  $A + B = (a_{ij} + b_{ij})$
- Scalar multiplication  $aB = (a b_{ij})$
- Matrix multiplication  $AB = \left( \sum_k a_{ik} b_{kj} \right)$

In words: The  $i, j$  element of  $AB$  is the inner product of row  $i$  of  $A$  with column  $j$  of  $B$ .

- Inverse:  $A^{-1}A = AA^{-1} = I$
- Transpose  $A' = (a_{ji})$
- Symmetric matrices:  $A = A'$
- Determinants
- Linear independence

# Inverses: Proving $B = A^{-1}$

- $B = A^{-1}$  means  $AB = BA = I$ .
- It looks like you have two things to show.
- But if  $A$  and  $B$  are square matrices of the same size, you only need to do it in one direction.

# Theorem

If  $A$  and  $B$  are square matrices and  $AB = I$ , then  $A$  and  $B$  are inverses.

**Proof:** Suppose  $AB = I$

- $A$  and  $B$  must both have inverses, for otherwise  $|AB| = |A||B| = 0 \neq |I| = 1$ . Now,
- $AB = I \Rightarrow ABB^{-1} = IB^{-1} \Rightarrow A = B^{-1}$ .
- $AB = I \Rightarrow A^{-1}AB = A^{-1}I \Rightarrow B = A^{-1}$ .

# How to show $A^{-1'} = A'^{-1}$

- Let  $B = A^{-1}$ .
- Want to prove that  $B'$  is the inverse of  $A'$ .
- It is enough to show that  $B'A' = I$ .
- $AB = I \Rightarrow B'A' = I' = I$  ■

## Three mistakes that will get you a zero

Numbers are  $1 \times 1$  matrices, but larger matrices are not just numbers.

You will get a zero if you

- Write  $AB = BA$ . It's not true in general.
- Write  $A^{-1}$  when  $A$  is not a square matrix. The inverse is not even defined.
- Represent the inverse of a matrix (even if it exists) by writing it in the denominator, like  $\mathbf{a}'B^{-1}\mathbf{a} = \frac{\mathbf{a}'\mathbf{a}}{B}$ .

Matrices are not just numbers.

If you commit one of these crimes, the mark for the question (or part of a question, like 3c) is zero. The rest of your answer will be ignored, and will also get a zero.

## Half marks off, at least

You will lose *at least* half marks for writing a product like  $AB$  when the number of columns in  $A$  does not equal the number of rows in  $B$ .



# Linear combination of vectors

Let  $\mathbf{x}_1, \dots, \mathbf{x}_p$  be  $n \times 1$  vectors and  $a_1, \dots, a_p$  be scalars. A *linear combination* of the vectors is

$$\begin{aligned} \mathbf{c} &= a_1 \mathbf{x}_1 + a_2 \mathbf{x}_2 + \cdots + a_p \mathbf{x}_p \\ &= a_1 \begin{pmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{n1} \end{pmatrix} + a_2 \begin{pmatrix} x_{12} \\ x_{22} \\ \vdots \\ x_{n2} \end{pmatrix} + \cdots + a_p \begin{pmatrix} x_{1p} \\ x_{2p} \\ \vdots \\ x_{np} \end{pmatrix} \end{aligned}$$

# Linear independence

A set of vectors  $\mathbf{x}_1, \dots, \mathbf{x}_p$  is said to be *linearly dependent* if there is a set of scalars  $a_1, \dots, a_p$ , not all zero, with

$$a_1 \begin{pmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{n1} \end{pmatrix} + a_2 \begin{pmatrix} x_{12} \\ x_{22} \\ \vdots \\ x_{n2} \end{pmatrix} + \dots + a_p \begin{pmatrix} x_{1p} \\ x_{2p} \\ \vdots \\ x_{np} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

If no such constants  $a_1, \dots, a_p$  exist, the vectors are linearly independent. That is,

If  $a_1\mathbf{x}_1 + a_2\mathbf{x}_2 + \dots + a_p\mathbf{x}_p = \mathbf{0}$  implies  $a_1 = a_2 = \dots = a_p = 0$ , then the vectors are said to be *linearly independent*.

Bind the vectors  $\mathbf{x}_1, \dots, \mathbf{x}_p$  into a matrix

$$\begin{aligned}
& a_1 \mathbf{x}_1 + a_2 \mathbf{x}_2 + \dots + a_p \mathbf{x}_p \\
= & \begin{pmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{n1} \end{pmatrix} a_1 + \begin{pmatrix} x_{12} \\ x_{22} \\ \vdots \\ x_{n2} \end{pmatrix} a_2 + \dots + \begin{pmatrix} x_{1p} \\ x_{2p} \\ \vdots \\ x_{np} \end{pmatrix} a_p \\
= & \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1p} \\ x_{21} & x_{22} & \dots & x_{2p} \\ \vdots & \vdots & \vdots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{np} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_p \end{pmatrix} \\
= & \mathbf{X} \mathbf{a}
\end{aligned}$$

## A more convenient definition of linear independence

$$a_1\mathbf{x}_1 + a_2\mathbf{x}_2 + \cdots + a_p\mathbf{x}_p = X\mathbf{a}$$

Let  $X$  be an  $n \times p$  matrix of constants. The columns of  $X$  are said to be *linearly dependent* if there exists  $\mathbf{a} \neq \mathbf{0}$  with  $X\mathbf{a} = \mathbf{0}$ . We will say that the columns of  $X$  are *linearly independent* if  $X\mathbf{a} = \mathbf{0}$  implies  $\mathbf{a} = \mathbf{0}$ .

For example, show that the existence of  $B^{-1}$  implies that the columns of  $B$  are linearly independent.

$$B\mathbf{a} = \mathbf{0} \Rightarrow B^{-1}B\mathbf{a} = B^{-1}\mathbf{0} \Rightarrow \mathbf{a} = \mathbf{0} \quad \blacksquare$$

# Trace of a square matrix

- Sum of diagonal elements
- Obvious:  $tr(A + B) = tr(A) + tr(B)$
- Not obvious:  $tr(AB) = tr(BA)$
- Even though  $AB \neq BA$ .

$$\text{tr}(AB) = \text{tr}(BA)$$

Let  $A$  be  $p \times q$  and  $B$  be  $q \times p$ , so that  $AB$  is  $p \times p$  and  $BA$  is  $q \times q$ .

First, agree that  $\sum_{i=1}^n x_i = \sum_{j=1}^n x_j$ .

$$\begin{aligned} \text{tr}(AB) &= \text{tr}\left(\sum_{k=1}^q a_{ik}b_{kj}\right) \\ &= \sum_{i=1}^p \sum_{k=1}^q a_{ik}b_{ki} \\ &= \sum_{k=1}^q \sum_{i=1}^p b_{ki}a_{ik} \\ &= \sum_{i=1}^q \sum_{k=1}^p b_{ik}a_{ki} \\ &= \text{tr}\left(\sum_{k=1}^p b_{ik}a_{kj}\right) \\ &= \text{tr}(BA) \end{aligned}$$

# Eigenvalues and eigenvectors

Let  $A = [a_{i,j}]$  be an  $n \times n$  matrix, so that the following applies to square matrices.  $A$  is said to have an *eigenvalue*  $\lambda$  and (non-zero) *eigenvector*  $\mathbf{x} \neq \mathbf{0}$  corresponding to  $\lambda$  if

$$A\mathbf{x} = \lambda\mathbf{x}.$$

Eigenvectors can be scaled to have length one, so that  $\mathbf{x}'\mathbf{x} = 1$ .

- Eigenvalues are the  $\lambda$  values that solve the determinantal equation  $|A - \lambda I| = 0$ .
- The determinant is the product of the eigenvalues:

$$|A| = \prod_{i=1}^n \lambda_i$$

# Spectral decomposition of symmetric matrices

The *Spectral decomposition theorem* says that every square and symmetric matrix  $A = [a_{i,j}]$  may be written

$$A = CDC',$$

where the columns of  $C$  (which may also be denoted  $\mathbf{x}_1, \dots, \mathbf{x}_n$ ) are the eigenvectors of  $A$ , and the diagonal matrix  $D$  contains the corresponding eigenvalues.

$$D = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}$$

The eigenvectors may be chosen to be orthonormal, so that  $C$  is an orthogonal matrix. That is,  $CC' = C'C = I$ .



# Positive definite matrices

The  $n \times n$  matrix  $A$  is said to be *positive definite* if

$$\mathbf{y}'A\mathbf{y} > 0$$

for *all*  $n \times 1$  vectors  $\mathbf{y} \neq \mathbf{0}$ . It is called *non-negative definite* (or sometimes positive semi-definite) if  $\mathbf{y}'A\mathbf{y} \geq 0$ .

## Example: Show $X'X$ non-negative definite

Let  $X$  be an  $n \times p$  matrix of real constants and let  $\mathbf{y}$  be  $p \times 1$ . Then  $\mathbf{z} = X\mathbf{y}$  is  $n \times 1$ , and

$$\begin{aligned} & \mathbf{y}'(X'X)\mathbf{y} \\ = & (X\mathbf{y})'(X\mathbf{y}) \\ = & \mathbf{z}'\mathbf{z} \\ = & \sum_{i=1}^n z_i^2 \geq 0 \quad \blacksquare \end{aligned}$$

# Some properties of symmetric positive definite matrices

Variance-covariance matrices are often assumed positive definite.

For a symmetric matrix,

Positive definite



All eigenvalues positive



Inverse exists  $\Leftrightarrow$  Columns (rows) linearly independent.

If a real symmetric matrix is also non-negative definite, as a variance-covariance matrix *must* be, Inverse exists  $\Rightarrow$  Positive definite

Showing Positive definite  $\Rightarrow$  Eigenvalues positive

Let the  $p \times p$  matrix  $A$  be positive definite, so that  $\mathbf{y}'A\mathbf{y} > 0$  for all  $\mathbf{y} \neq \mathbf{0}$ .

$\lambda$  an eigenvalue means  $A\mathbf{x} = \lambda\mathbf{x}$  with  $\mathbf{x}'\mathbf{x} = 1$ .

$\Rightarrow \mathbf{x}'A\mathbf{x} = \mathbf{x}'\lambda\mathbf{x} = \lambda\mathbf{x}'\mathbf{x} = \lambda > 0$ . ■

# Inverse of a diagonal matrix

To set things up

Suppose  $D = [d_{i,j}]$  is a diagonal matrix with non-zero diagonal elements. It is easy to verify that

$$\begin{pmatrix} 1/d_{1,1} & 0 & \cdots & 0 \\ 0 & 1/d_{2,2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1/d_{n,n} \end{pmatrix} \begin{pmatrix} d_{1,1} & 0 & \cdots & 0 \\ 0 & d_{2,2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_{n,n} \end{pmatrix} = I$$

So  $D^{-1}$  exists.

# Showing Eigenvalues positive $\Rightarrow$ Inverse exists

For a symmetric, positive definite matrix

Let  $A$  be symmetric and positive definite. Then  $A = CDC'$ , and its eigenvalues are positive.

Let  $B = CD^{-1}C'$ . Show  $B = A^{-1}$ .

$$AB = CDC'CD^{-1}C' = I$$

So

$$A^{-1} = CD^{-1}C'$$

# Square root matrices

For symmetric, non-negative definite matrices

To set things up, define

$$D^{1/2} = \begin{pmatrix} \sqrt{\lambda_1} & 0 & \cdots & 0 \\ 0 & \sqrt{\lambda_2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sqrt{\lambda_n} \end{pmatrix}$$

So that

$$\begin{aligned} D^{1/2} D^{1/2} &= \begin{pmatrix} \sqrt{\lambda_1} & 0 & \cdots & 0 \\ 0 & \sqrt{\lambda_2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sqrt{\lambda_n} \end{pmatrix} \begin{pmatrix} \sqrt{\lambda_1} & 0 & \cdots & 0 \\ 0 & \sqrt{\lambda_2} & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sqrt{\lambda_n} \end{pmatrix} \\ &= \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix} = D \end{aligned}$$

For a non-negative definite, symmetric matrix  $A$ 

Define

$$A^{1/2} = CD^{1/2}C'$$

So that

$$\begin{aligned}A^{1/2}A^{1/2} &= CD^{1/2}C'CD^{1/2}C' \\ &= CD^{1/2}ID^{1/2}C' \\ &= CD^{1/2}D^{1/2}C' \\ &= CDC' \\ &= A\end{aligned}$$



# The square root of the inverse is the inverse of the square root

Let  $A$  be symmetric and positive definite, with  $A = CDC'$ .

Let  $B = CD^{-1/2}C'$ . What is  $D^{-1/2}$ ?

Show  $B = (A^{-1})^{1/2}$ .

$$\begin{aligned} BB &= CD^{-1/2}C'CD^{-1/2}C' \\ &= CD^{-1}C' = A^{-1} \end{aligned}$$

Show  $B = (A^{1/2})^{-1}$

$$A^{1/2}B = CD^{1/2}C'CD^{-1/2}C' = I$$

Just write  $A^{-1/2} = CD^{-1/2}C'$

# Extras

You may not know about these, but we may use them occasionally

- Rank
- Partitioned matrices

# Rank

- Row rank is the number of linearly independent rows.
- Column rank is the number of linearly independent columns.
- Rank of a matrix is the minimum of row rank and column rank.
- $\text{rank}(AB) = \min(\text{rank}(A), \text{rank}(B))$ .

# Partitioned matrix

- A matrix of matrices

$$\left[ \begin{array}{c|c} A & B \\ \hline C & D \end{array} \right]$$

- Row by column (matrix) multiplication works, provided the matrices are the right sizes.

# Matrix calculation with R

```
> is.matrix(3) # Is the number 3 a 1x1 matrix?
```

```
[1] FALSE
```

```
> treecorr = cor(trees); treecorr
```

```
      Girth    Height    Volume
Girth  1.0000000 0.5192801 0.9671194
Height 0.5192801 1.0000000 0.5982497
Volume 0.9671194 0.5982497 1.0000000
```

```
> is.matrix(treecorr)
```

```
[1] TRUE
```

# Creating matrices

## Bind rows into a matrix

```
> # Bind rows of a matrix together
> A = rbind( c(3, 2, 6,8),
+           c(2,10,-7,4),
+           c(6, 6, 9,1) ); A
```

```
      [,1] [,2] [,3] [,4]
[1,]    3    2    6    8
[2,]    2   10   -7    4
[3,]    6    6    9    1
```

```
> # Transpose
> t(A)
```

```
      [,1] [,2] [,3]
[1,]    3    2    6
[2,]    2   10    6
[3,]    6   -7    9
[4,]    8    4    1
```

# Matrix multiplication

Remember,  $A$  is  $3 \times 4$

```
> # U = AA' (3x3), V = A'A (4x4)
> U = A %% t(A)
> V = t(A) %% A; V
```

|      | [,1] | [,2] | [,3] | [,4] |
|------|------|------|------|------|
| [1,] | 49   | 62   | 58   | 38   |
| [2,] | 62   | 140  | -4   | 62   |
| [3,] | 58   | -4   | 166  | 29   |
| [4,] | 38   | 62   | 29   | 81   |

# Determinants

```
> # U = AA' (3x3), V = A'A (4x4)
> # So rank(V) cannot exceed 3 and det(V)=0
> det(U); det(V)
```

```
[1] 1490273
```

```
[1] -3.622862e-09
```

Inverse of  $U$  exists, but inverse of  $V$  does not.



# Inverses

- The `solve` function is for solving systems of linear equations like  $M\mathbf{x} = \mathbf{b}$ .
- Just typing `solve(M)` gives  $M^{-1}$ .

```
> # Recall U = AA' (3x3), V = A'A (4x4)
> solve(U)
```

```

           [,1]           [,2]           [,3]
[1,]  0.0173505123 -8.508508e-04 -1.029342e-02
[2,] -0.0008508508  5.997559e-03  2.013054e-06
[3,] -0.0102934160  2.013054e-06  1.264265e-02
```

```
> solve(V)
```

```
Error in solve.default(V) :
  system is computationally singular: reciprocal condition
  number = 6.64193e-18
```

# Eigenvalues and eigenvectors

```
> # Recall  $U = AA'$  (3x3),  $V = A'A$  (4x4)  
> eigen(U)
```

```
$values
```

```
[1] 234.01162 162.89294 39.09544
```

```
$vectors
```

```
          [,1]          [,2]          [,3]  
[1,] -0.6025375  0.1592598  0.78203893  
[2,] -0.2964610 -0.9544379 -0.03404605  
[3,] -0.7409854  0.2523581 -0.62229894
```

## $V$ should have at least one zero eigenvalue

Because  $A$  is  $3 \times 4$ ,  $V = A'A$ , and the rank of a product is the minimum rank of the matrices.

```
> eigen(V)
```

```
$values
```

```
[1] 2.340116e+02 1.628929e+02 3.909544e+01 -1.012719e-14
```

```
$vectors
```

```
      [,1]      [,2]      [,3]      [,4]  
[1,] -0.4475551  0.006507269 -0.2328249  0.863391352  
[2,] -0.5632053 -0.604226296 -0.4014589 -0.395652773  
[3,] -0.5366171  0.776297432 -0.1071763 -0.312917928  
[4,] -0.4410627 -0.179528649  0.8792818  0.009829883
```

Spectral decomposition  $V = CDC'$ 

```
> eigenV = eigen(V)
> C = eigenV$vectors; D = diag(eigenV$values); D
```

```
      [,1]      [,2]      [,3]      [,4]
[1,] 234.0116  0.0000  0.00000  0.000000e+00
[2,]  0.0000 162.8929  0.00000  0.000000e+00
[3,]  0.0000  0.0000 39.09544  0.000000e+00
[4,]  0.0000  0.0000  0.00000 -1.012719e-14
```

```
> # C is an orthogonal matrix
> C %% t(C)
```

```
      [,1]      [,2]      [,3]      [,4]
[1,] 1.000000e+00 5.551115e-17 0.000000e+00 -3.989864e-17
[2,] 5.551115e-17 1.000000e+00 2.636780e-16 3.556183e-17
[3,] 0.000000e+00 2.636780e-16 1.000000e+00 2.558717e-16
[4,] -3.989864e-17 3.556183e-17 2.558717e-16 1.000000e+00
```

Verify  $V = CDC'$ 

```
> V; C %% D %% t(C)
```

```
      [,1] [,2] [,3] [,4]
[1,]   49   62   58   38
[2,]   62  140   -4   62
[3,]   58   -4  166   29
[4,]   38   62   29   81
```

```
      [,1] [,2] [,3] [,4]
[1,]   49   62   58   38
[2,]   62  140   -4   62
[3,]   58   -4  166   29
[4,]   38   62   29   81
```

# Square root matrix $V^{1/2} = CD^{1/2}C'$

```
> sqrtV = C %*% sqrt(D) %*% t(C)
```

Warning message:

In sqrt(D) : NaNs produced

```
> # Multiply to get V
```

```
> sqrtV %*% sqrtV; V
```

```
      [,1] [,2] [,3] [,4]
[1,] NaN  NaN  NaN  NaN
[2,] NaN  NaN  NaN  NaN
[3,] NaN  NaN  NaN  NaN
[4,] NaN  NaN  NaN  NaN
      [,1] [,2] [,3] [,4]
[1,]  49   62   58   38
[2,]  62  140   -4   62
[3,]  58   -4  166   29
[4,]  38   62   29   81
```

# What happened?

```
> D; sqrt(D)
```

```
      [,1]      [,2]      [,3]      [,4]
[1,] 234.0116  0.0000  0.00000  0.000000e+00
[2,]  0.0000 162.8929  0.00000  0.000000e+00
[3,]  0.0000  0.0000 39.09544  0.000000e+00
[4,]  0.0000  0.0000  0.00000 -1.012719e-14
```

```
      [,1]      [,2]      [,3] [,4]
[1,] 15.29744  0.00000  0.000000  0
[2,]  0.00000 12.76295  0.000000  0
[3,]  0.00000  0.00000  6.252635  0
[4,]  0.00000  0.00000  0.000000 NaN
```

Warning message:

In sqrt(D) : NaNs produced

## Copyright Information

This slide show was prepared by **Jerry Brunner**, Department of Statistical Sciences, University of Toronto. It is licensed under a **Creative Commons Attribution - ShareAlike 3.0 Unported License**. Use any part of it as you like and share the result freely. The L<sup>A</sup>T<sub>E</sub>X source code is available from the course website:

<http://www.utstat.toronto.edu/~brunner/oldclass/302f17>