

Influent Ob- servations

(1)

Looking for trouble with the model.

Let $H = [h_{ij}]$, diagonal elements are h_{ii} . Moral of the story is small h_{ii} are good & big h_{ii} are bad.

(a) Average h_{ii} is small

$$\text{tr}(H) = \text{tr}(X(X'X)^{-1}X') = k+1$$

$$\text{and } \frac{1}{n} \sum_{i=1}^n h_{ii} = \frac{k+1}{n} \rightarrow 0$$

(b) $0 \leq h_{ii} \leq 1$

First H is non-negative definite

$$\begin{aligned} v' H v &= v' H' H v = (Hv)' H v = z' z \\ &= \sum_{j=1}^n z_j^2 \geq 0 \end{aligned}$$

Letting $v = 0$ except for a 1 in position i

$$v' H v = h_{ii} \geq 0$$

next.

$$\begin{aligned}
\text{cov}(e) &= \text{cov}((I-H)y) \\
&= (I-H)\sigma^2(I-H)' \\
&= \sigma^2(I-H)
\end{aligned}$$

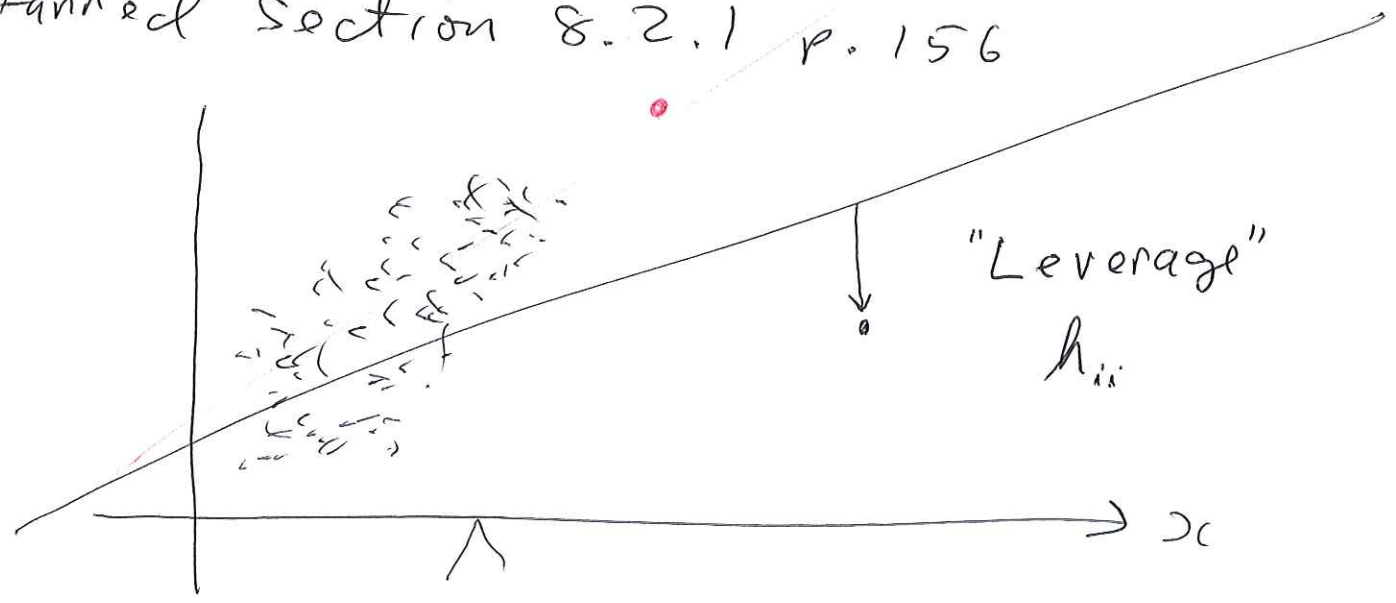
So $\text{var}(e_i) = \sigma^2(1-h_{ii}) \geq 0$

So $h_{ii} \leq 1$ & hence $0 \leq h_{ii} \leq 1$

now of X^i

(c) h_{ii} indirectly reflects how far x_i is from \bar{x} , vector of sample IV means. "centroid"

Stanned section 8.2.1 p. 156



(1) Residuals e_i reflect ε_i better when h_{ii} are small. (3)

$$y = X\beta + \varepsilon$$

$$\hat{y} = Xb + e$$

Denote cols (rows) of H by $H = \begin{pmatrix} h_1 & & \\ \vdots & \ddots & \\ h_n & & \end{pmatrix}$

$$H = H H = h_i' h_i = h_{ii}$$

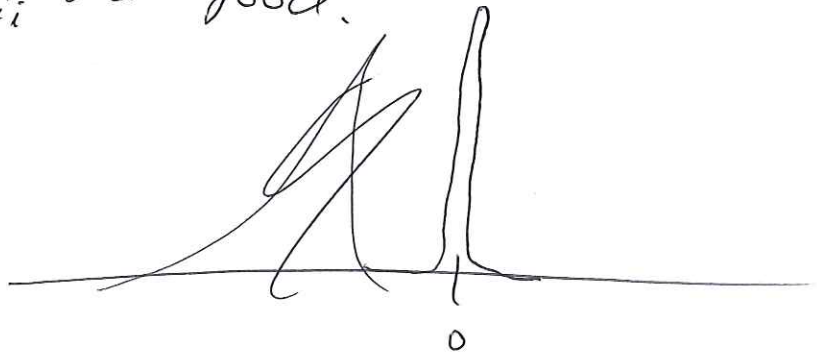
using $e = M\varepsilon = (I - H)\varepsilon = \varepsilon - H\varepsilon$

so

$$e_i = \varepsilon_i - \underbrace{h_i' \varepsilon}_{\text{difference term}}$$

$$h_i' \varepsilon \sim N(0, \sigma^2 h_i' h_i) = N(0, \sigma^2 h_{ii})$$

And small h_{ii} are good.



② $DFBETA = b - b(i)$ Transpose of row i

$$= \frac{(X'X)^{-1} x_i e_i}{1 - h_{ii}}$$

(8.8), p. 158

DFBETAS: e_i^* instead of e_i

③ $DFFIT = \hat{y}_i - \hat{y}(i) = \frac{h_{ii} e_i}{1 - h_{ii}}$

↑
p. 157

DFFITS
use e_i^*

④ Thm 5.1, p. 106

~~Tests are n.~~

Normality does not matter for tests & CIs provided $\max(h_{ii}) \rightarrow 0$ as $n \rightarrow \infty$

Ⓢ Rule of thumb

$$\max(h_{ii}) < 0.2$$