

Name Jerry

Student Number _____

STA 302f 2015 Test 1B

1. (15 Points) Let $\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{pmatrix}$, and let $\mathbf{x} = \begin{pmatrix} 3 \\ 0 \\ 1 \end{pmatrix}$. Calculate $\mathbf{x}'\mathbf{A}$. Show at least one intermediate step and **circle your final answer**.

$$\mathbf{x}'\mathbf{A} = (3 \ 0 \ 1) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{pmatrix}$$

$$= (3, -2, 1)$$

2. (30 Points) This simple regression model has an unknown intercept, but the slope is fixed at one. Let $Y_i = \beta_0 + x_i + \epsilon_i$ for $i = 1, \dots, n$, where $\epsilon_1, \dots, \epsilon_n$ are a random sample (that is, independent and independently distributed) from a distribution with expected value zero and variance σ^2 , and β_0 and σ^2 are unknown constants. The numbers x_1, \dots, x_n are known, observed constants.

- (a) Find the least squares estimate of β_0 by minimizing the function

$$Q(\beta_0) = \sum_{i=1}^n (Y_i - \beta_0 - x_i)^2$$

over all values of β_0 . Let $\hat{\beta}_0$ denote the point at which $Q(\beta_0)$ is minimal. Show your work. **Circle your final answer.** You need not bother with the second derivative test.

$$\frac{dQ}{d\beta_0} = \frac{d}{d\beta_0} \sum_{i=1}^n (Y_i - \beta_0 - x_i)^2 = \sum_{i=1}^n \frac{d}{d\beta_0} (Y_i - \beta_0 - x_i)^2$$

$$= \sum_{i=1}^n 2(Y_i - \beta_0 - x_i)(-1) \stackrel{set}{=} 0$$

$$\Rightarrow \sum_{i=1}^n Y_i - n\beta_0 - \sum_{i=1}^n x_i = 0$$

$$\Rightarrow n\beta_0 = \sum_{i=1}^n Y_i - \sum_{i=1}^n x_i \Rightarrow \beta_0 = \bar{Y} - \bar{x}, \text{ and}$$

$$\hat{\beta}_0 = \bar{Y} - \bar{x}$$

- (b) Calculate $\hat{\beta}_0$ for the following data set. The answer is a number. Show just a little work. **Circle your answer.**

x	4	6	7	5	3
y	6	4	2	2	1

$$\bar{x} = 25/5 = 5$$

$$\bar{y} = 15/5 = 3$$

$$\hat{\beta}_0 = \bar{y} - \bar{x} = 3 - 5 = -2$$

- (c) Continuing with Question 2, recall that an estimator is said to be *unbiased* if its expected value equals the parameter it is estimating. Is your $\hat{\beta}_0$ an unbiased estimator? Show the calculation in detail, and then write either the words "Yes, unbiased" or the words "No, biased." **Circle the words.** In this question, you are allowed to use any properties of expected value you know, without proof — even if they are not on the formula sheet.

$$\begin{aligned}
 E(\hat{\beta}_0) &= E(\bar{Y} - \bar{x}) = E(\bar{Y}) - \bar{x} \\
 &= E\left(\frac{1}{n} \sum_{i=1}^n Y_i\right) - \bar{x} = \frac{1}{n} \sum_{i=1}^n E(Y_i) - \bar{x} \\
 &= \frac{1}{n} \sum_{i=1}^n E(\beta_0 + x_i + \varepsilon_i) - \bar{x} \\
 &= \frac{1}{n} \sum_{i=1}^n (\beta_0 + x_i + E(\varepsilon_i)) - \bar{x} \\
 &= \frac{1}{n} (n\beta_0 + \sum x_i + 0) - \bar{x} \\
 &= \beta_0 + \bar{x} - \bar{x} = \beta_0
 \end{aligned}$$

Yes, unbiased

- (d) Calculate $\text{Var}(\hat{\beta}_0)$. Show your work. **Circle your answer.** In this question, you are allowed to use any properties of variance and covariance value you happen to know, without proof — even if they are not on the formula sheet.

$$\begin{aligned}
 \text{Var}(\hat{\beta}_0) &= \text{Var}(\bar{Y} - \bar{x}) = \text{Var}(\bar{Y}) \\
 &= \text{Var}\left(\frac{1}{n} \sum_{i=1}^n Y_i\right) \stackrel{\text{ind}}{=} \frac{1}{n^2} \sum_{i=1}^n \text{Var}(Y_i) \\
 &= \frac{1}{n^2} \sum_{i=1}^n \sigma^2 = \frac{n\sigma^2}{n^2} = \frac{\sigma^2}{n}
 \end{aligned}$$

$\frac{\sigma^2}{n}$

3. (10 Points) Let \mathbf{x}_1 , \mathbf{x}_2 and \mathbf{x}_3 be $p \times 1$ vectors of constants, with $3\mathbf{x}_1 + 5\mathbf{x}_2 = \mathbf{x}_3$. Prove that this set of vectors is linearly dependent. Use the definition on the formula sheet.

$$3\mathbf{x}_1 + 5\mathbf{x}_2 + (-1)\mathbf{x}_3 = \mathbf{0}$$

\uparrow \uparrow \uparrow
 a_1 a_2 a_3

a_i are not all zero.

4. (15 Points) Let \mathbf{A} and \mathbf{B} be non-singular matrices, meaning that their inverses exist. Let $\mathbf{C} = \mathbf{AB}$. Do one of these two things. Either

- (a) Give a formula for \mathbf{C}^{-1} and **circle the formula**. Then prove it is the inverse (you have two things to show), or
- (b) Show that \mathbf{C}^{-1} need not exist, by giving a simple numerical example using 2×2 matrices. You may use the fact that if the columns of \mathbf{C} are linearly dependent, it has no inverse.

Pick one and do it. Zero marks if you do both.

$$\mathbf{C}^{-1} = \mathbf{B}^{-1}\mathbf{A}^{-1}$$

$$\textcircled{1} \mathbf{B}^{-1}\mathbf{A}^{-1}\mathbf{C} = \mathbf{B}^{-1}\mathbf{A}^{-1}\mathbf{A}\mathbf{B} = \mathbf{B}^{-1}\mathbf{I}\mathbf{B} = \mathbf{B}^{-1}\mathbf{B} = \mathbf{I}$$

$$\textcircled{2} \mathbf{C}\mathbf{B}^{-1}\mathbf{A}^{-1} = \mathbf{A}\mathbf{B}\mathbf{B}^{-1}\mathbf{A}^{-1} = \mathbf{A}\mathbf{I}\mathbf{A}^{-1} = \mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$$

5. (15 Points) Let X_1 and X_2 be continuous random variables that are *independent*. Prove that $E(X_1^2 X_2^2) = E(X_1^2)E(X_2^2)$. Draw an arrow to the place in your answer where you use independence, and write "This is where I use independence." Because X_1 and X_2 are continuous, you will integrate.

$$E(X_1^2 X_2^2) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x_1^2 x_2^2 f_{X_1, X_2}(x_1, x_2) dx_1 dx_2$$

Independence

$$\stackrel{\downarrow}{=} \int \int x_1^2 x_2^2 f_{X_1}(x_1) f_{X_2}(x_2) dx_1 dx_2$$

$$= \int x_2^2 f_{X_2}(x_2) \left[\int x_1^2 f_{X_1}(x_1) dx_1 \right] dx_2$$

$$= \int x_2^2 f_{X_2}(x_2) E(X_1^2) dx_2$$

$$= E(X_1^2) \int x_2^2 f_{X_2}(x_2) dx_2$$

$$= E(X_1^2) E(X_2^2)$$



6. (15 Points) Let X_1 be a normal random variable with expected value 1 and variance 3. Let X_2 be a normal random variable with expected value 2 and variance 4. Furthermore, X_1 and X_2 are independent. Let $Y = X_1 + 3X_2$. Use moment-generating functions to find the distribution of Y . **Finish your answer with a clear statement of the distribution, including the numerical values of its parameters.**

$$M_{X_1}(t) = e^{1t + \frac{1}{2} 3t^2}$$

$$M_{X_2}(t) = e^{2t + \frac{1}{2} 4t^2}$$

$$M_Y(t) = M_{X_1 + 3X_2}(t) \stackrel{\text{ind}}{=} M_{X_1}(t) \cdot M_{3X_2}(t)$$

$$= M_{X_1}(t) M_{X_2}(3t)$$

$$= e^{t + \frac{1}{2} 3t^2} e^{2(3t) + \frac{1}{2} 4(3t)^2}$$

$$= e^{t + \frac{1}{2} 3t^2} e^{6t + \frac{1}{2} 36t^2}$$

$$= e^{7t + \frac{1}{2} 39t^2}$$

MGF of

Normal ($\mu=7, \sigma^2=39$)

Cross check

$$E(X_1 + 3X_2) = 1 + 6 = 7$$

$$\text{Var}(X_1 + 3X_2) = 3 + 9 \cdot 4 = 39 \checkmark$$